

# Imaging with Neutrons

**Hassina Bilheux**  
VENUS Instrument Scientist

**Yuxuan Zhang**  
MARS Instrument Scientist

**Jean Bilheux**  
Computational Instrument Scientist

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U.S. DEPARTMENT OF  
**ENERGY**

# The Neutron Imaging Team for the General User



Yuxuan Zhang,  
HFIR MARS Scientist



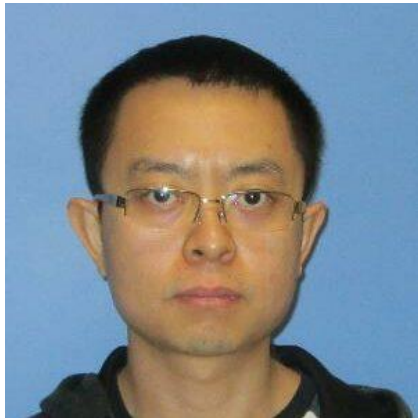
James Torres,  
HFIR MARS Scientist



Jean Bilheux,  
Computational  
Instrument Scientist



Shimin Tang, Artificial  
Intelligence, Machine  
Learning, Hyperspectral  
Imaging



Chen Zhang  
Imaging Software  
Developer



Roger Hobbs,  
Imaging Scientific  
Associate (SA)



Kevin Yahne,  
Imaging SA



Harley Skorpenske,  
SNS Group Leader



Hassina Bilheux,  
SNS VENUS Scientist

# Outline

- Imaging at the High Flux Isotope Reactor MARS beamline:
  - Principle of neutron radiography and computed tomography at a continuous source
  - The CG-1D imaging beamline
  - Examples
- Imaging at the Spallation Neutron Source:
  - Principle of neutron radiography at a pulsed source
  - Examples
  - ~~The VENUS !!!construction project~~
- Scientific programming

Yuxuan

Hassina

Jean

# Outline

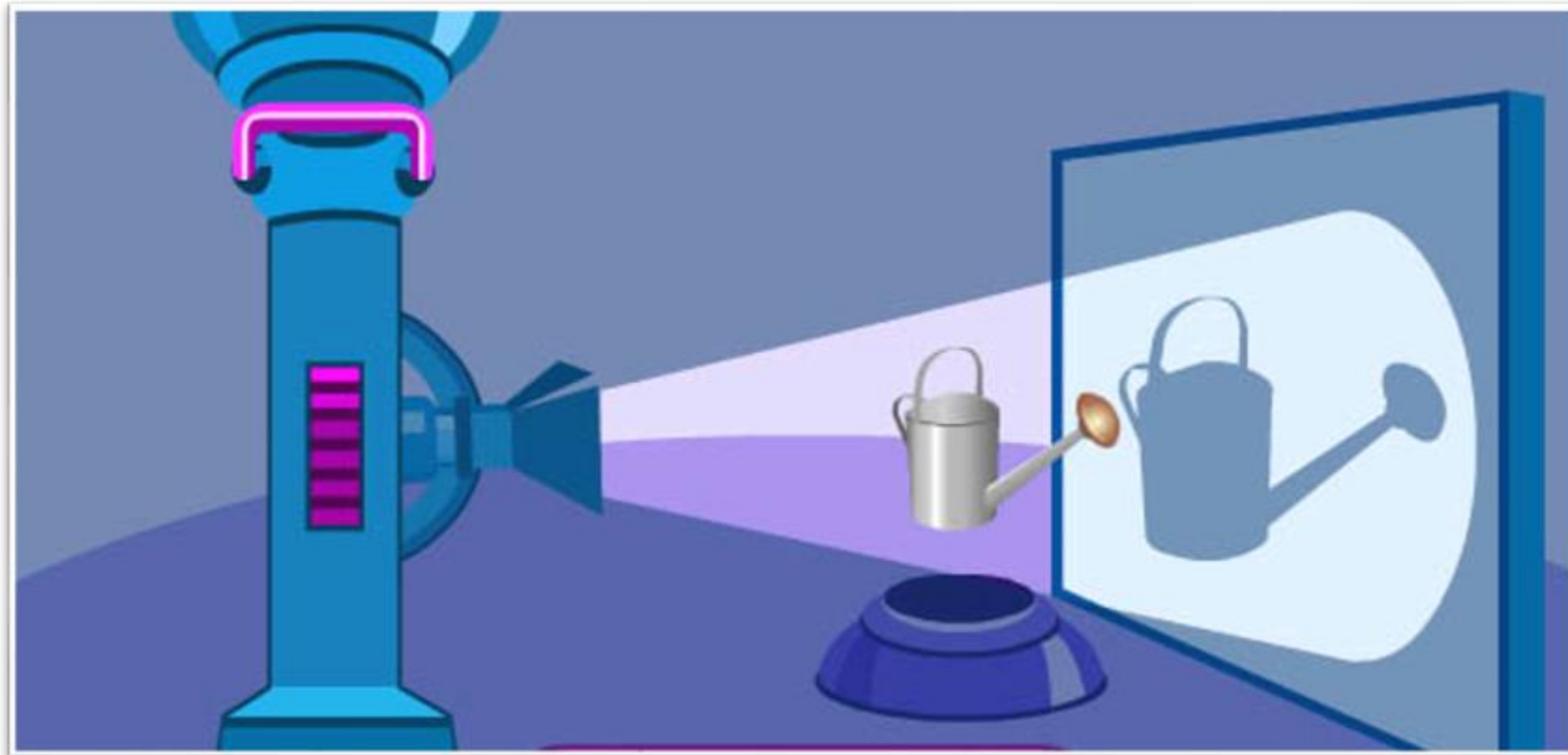
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Jean

# Neutron imaging measures the transmitted neutrons through an object

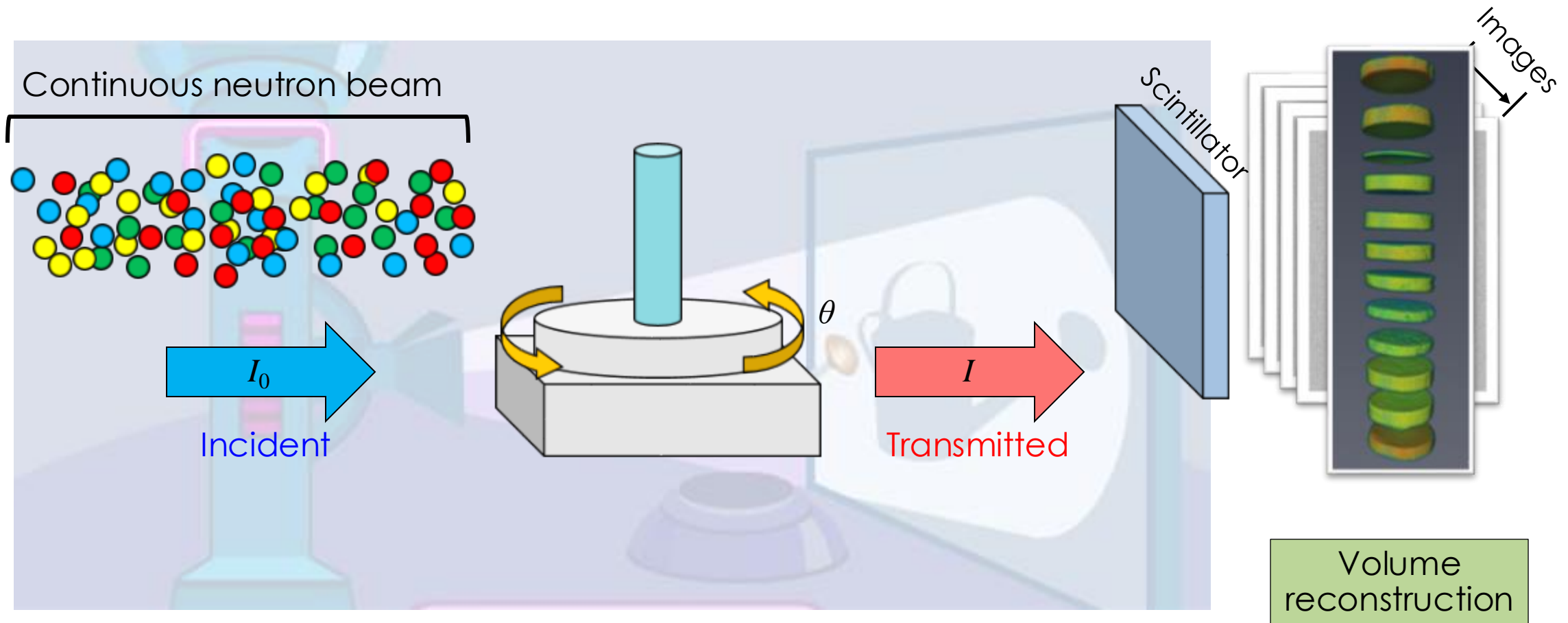


**Source**

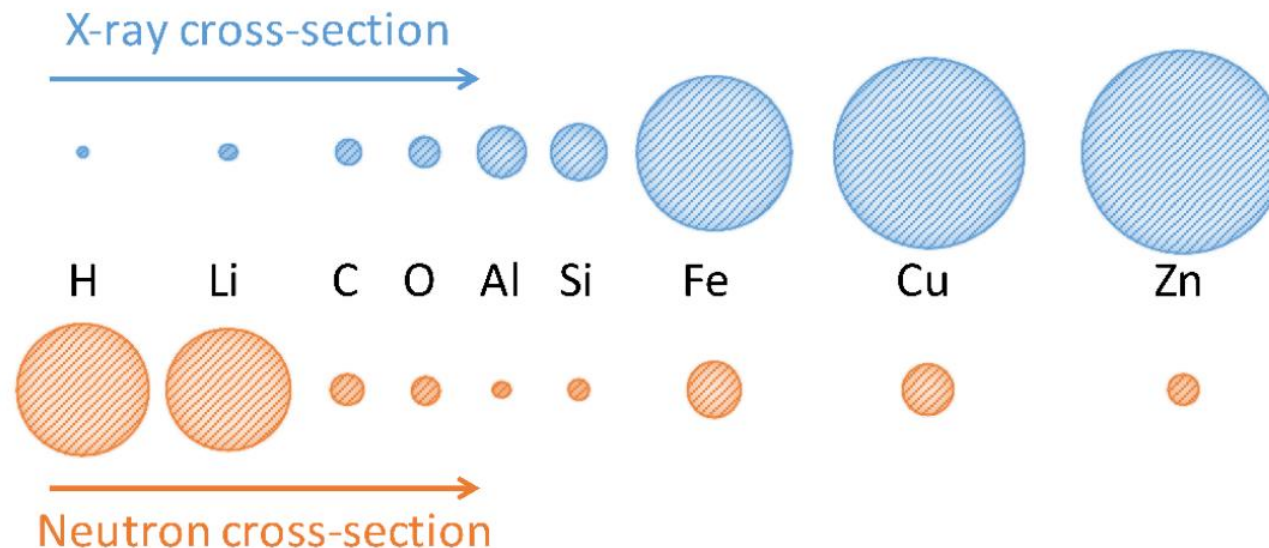
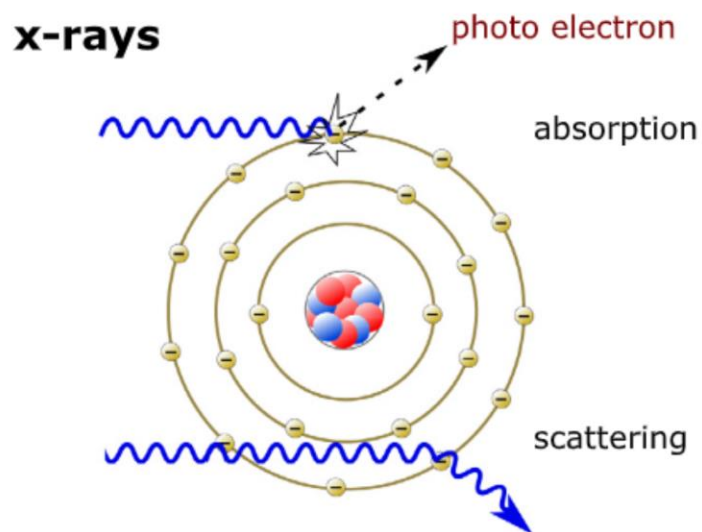
**Object**

**Detector**

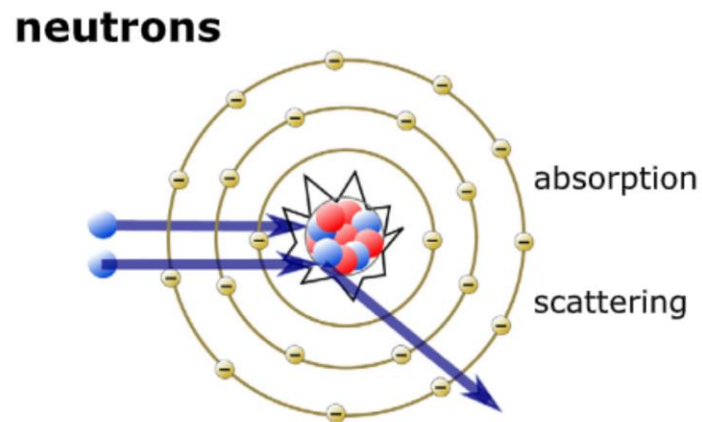
# Transmitted neutrons recorded as image/images



# Neutrons interact uniquely with matter

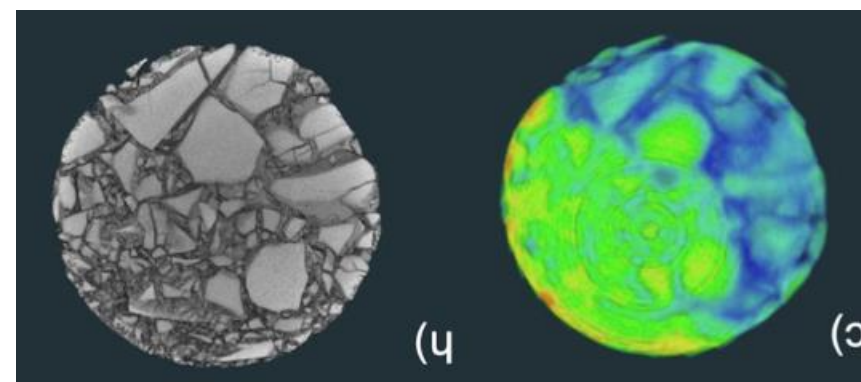
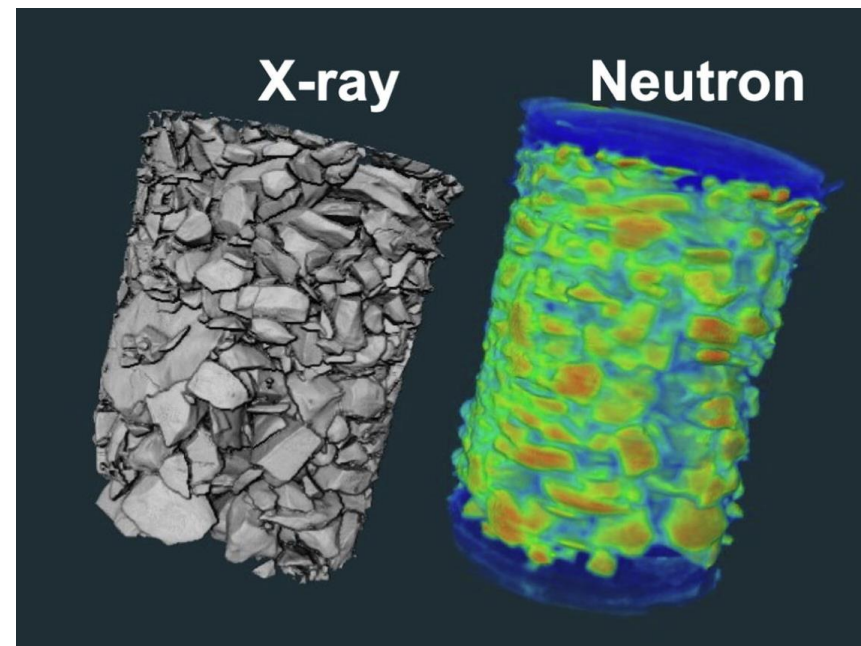
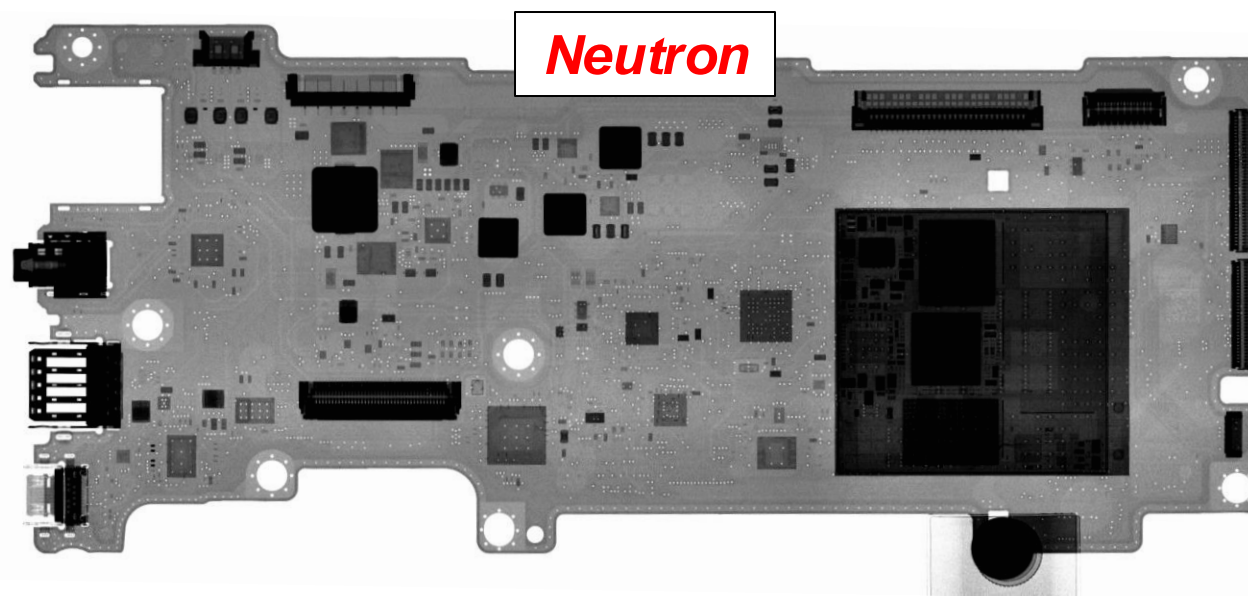
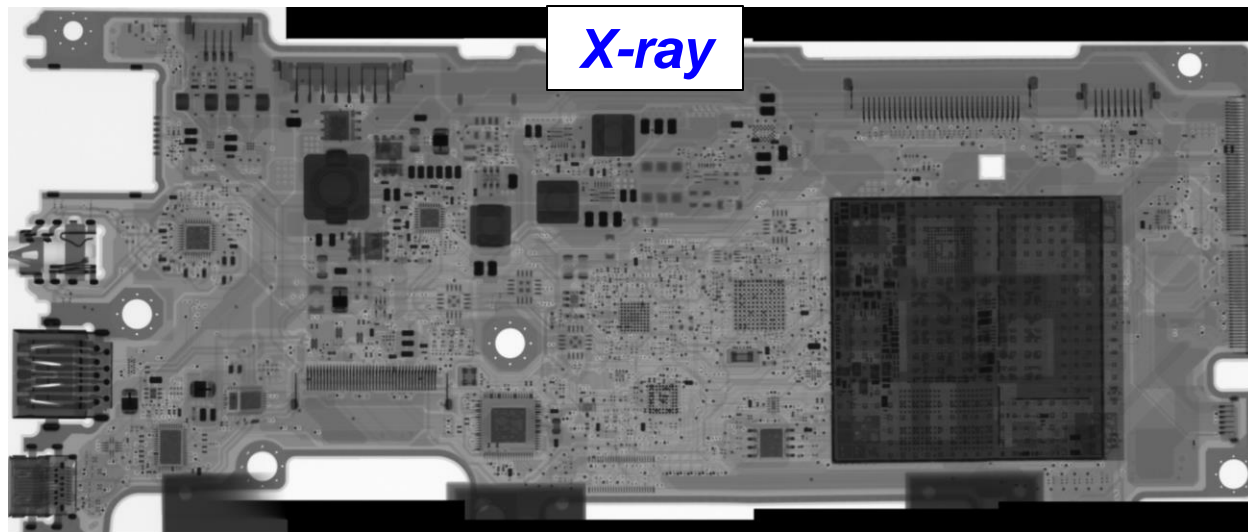


(Zhang Y. The University of Utah; 2016)



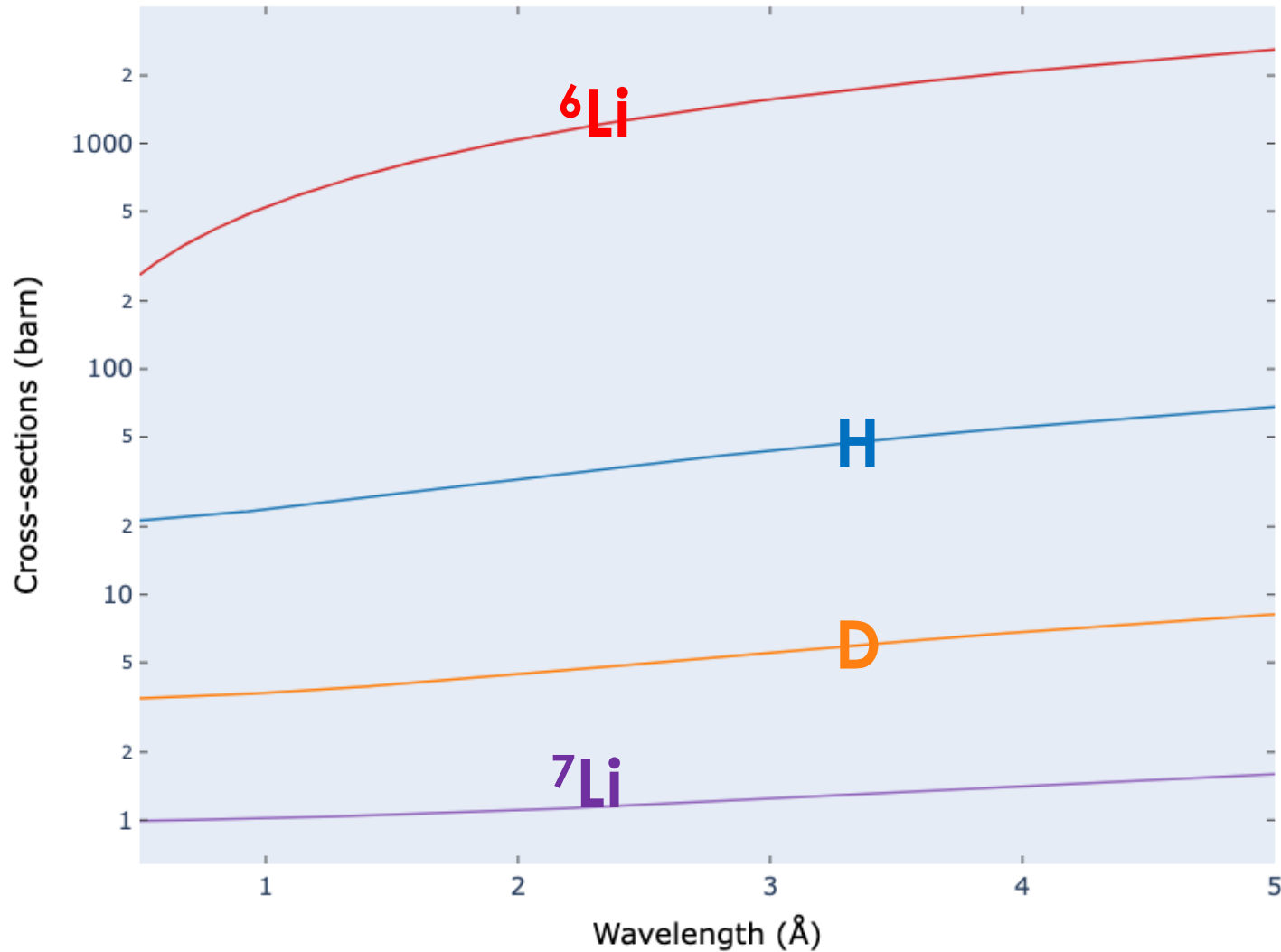
- **Non-destructive**
- **High penetration through metals**
- **Sensitive to light elements (H, Li, etc.)**
- **Isotopic contrast**

# Neutrons interact uniquely with matter (cont'd)



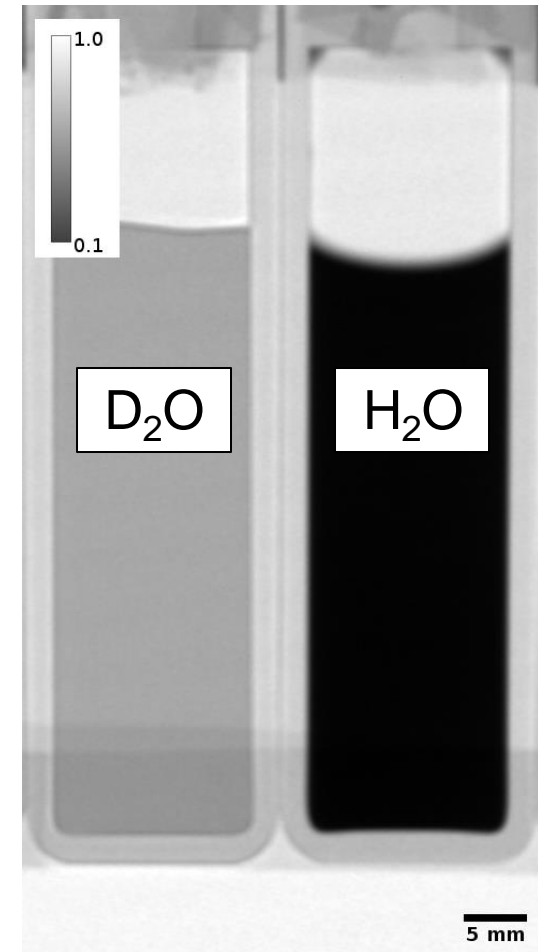


# Neutrons interact uniquely with matter (cont'd)



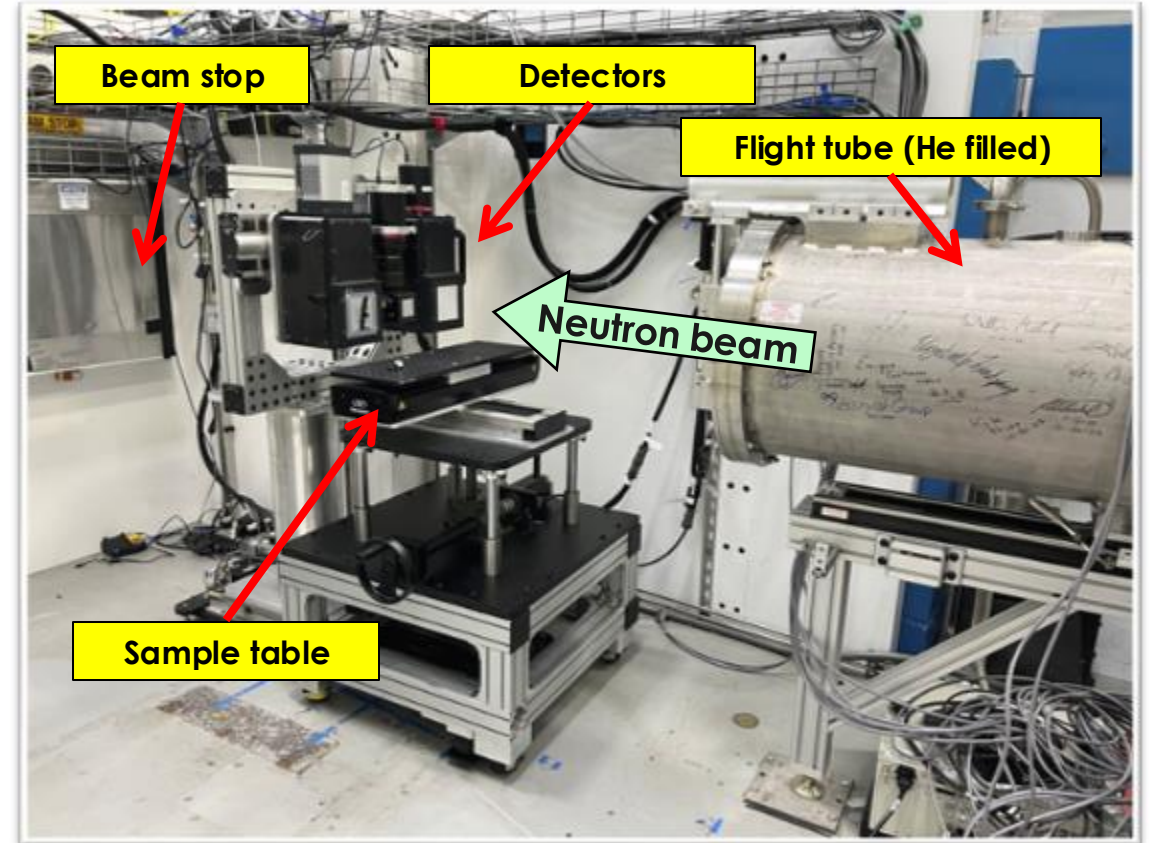
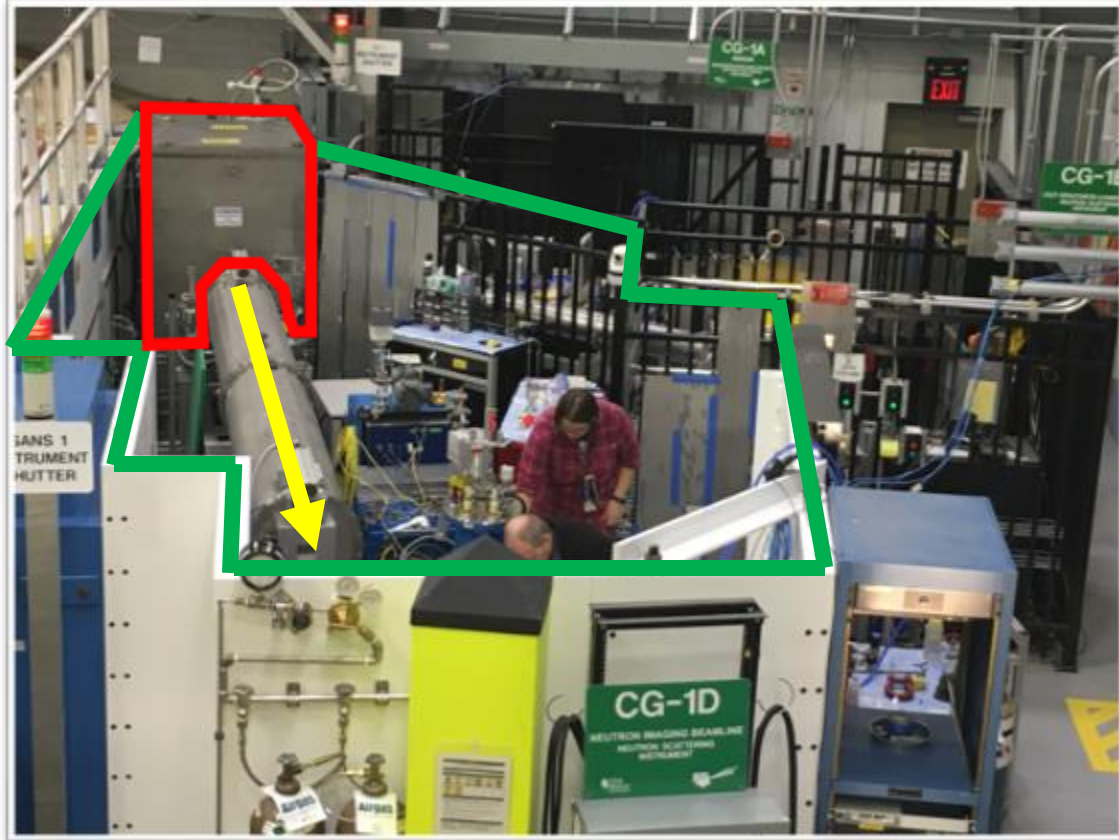
<https://neut.oml.gov/>

**Neutron**

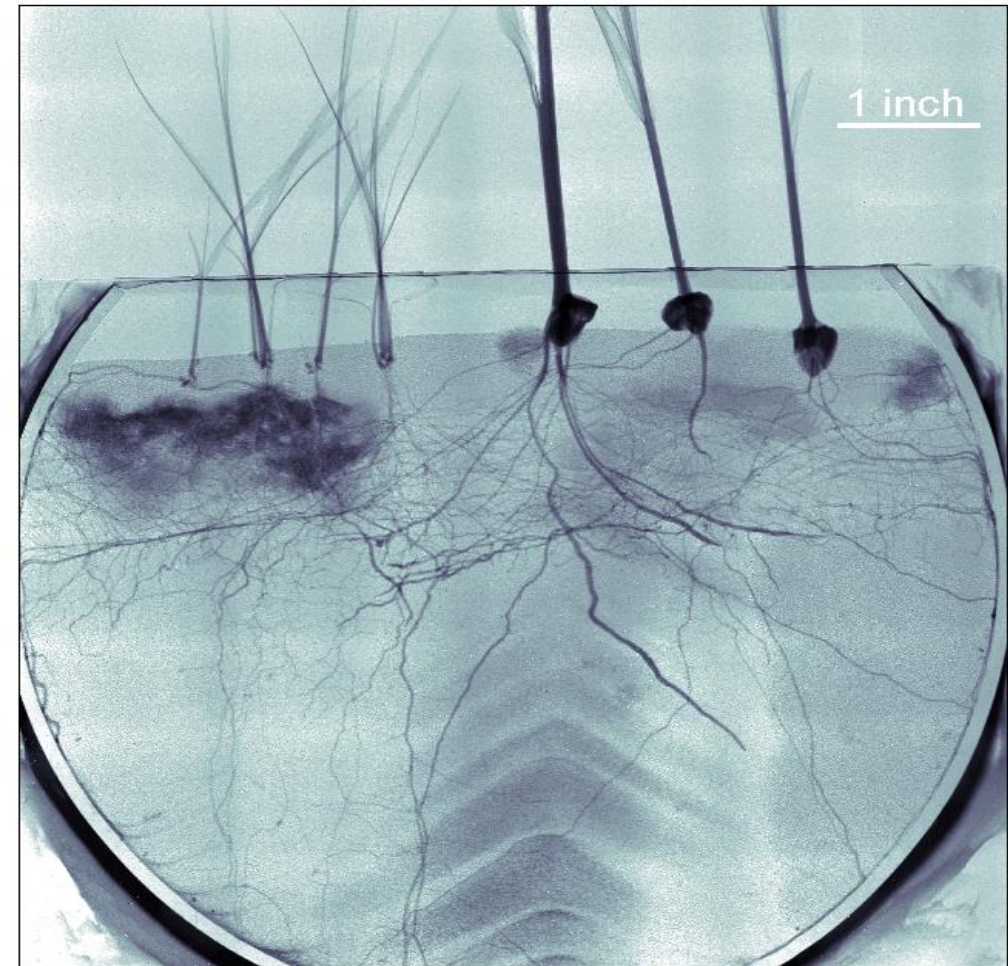
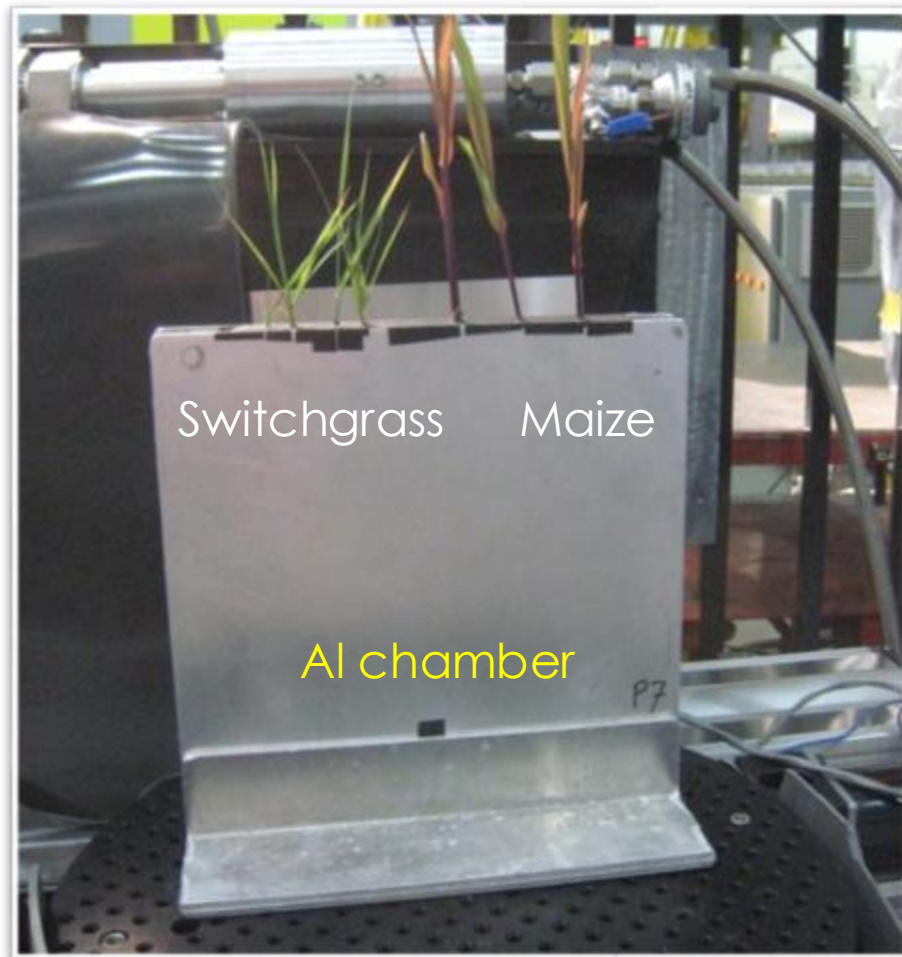


IPTS-26032, Y. Zhang, 2022

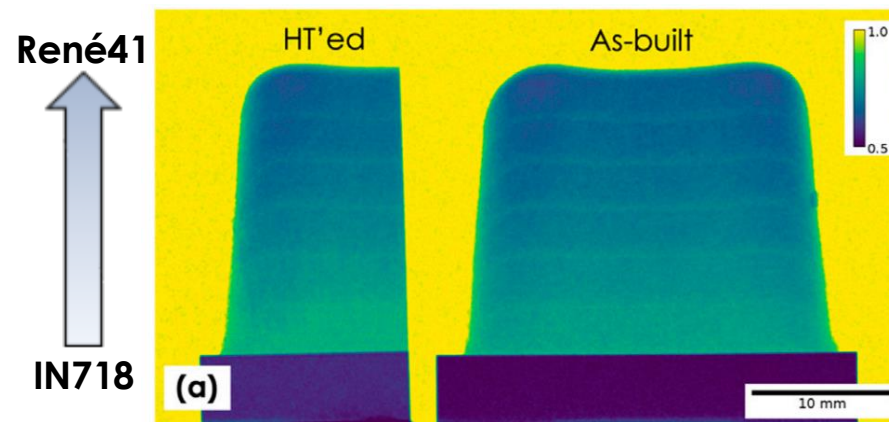
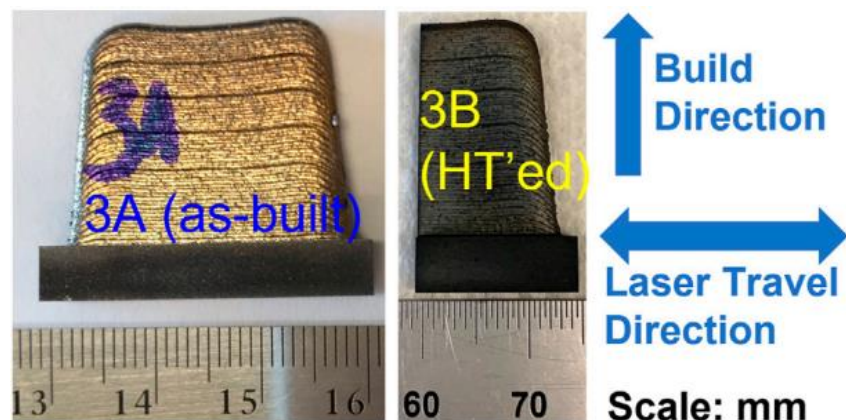
# The MARS instrument at HFIR



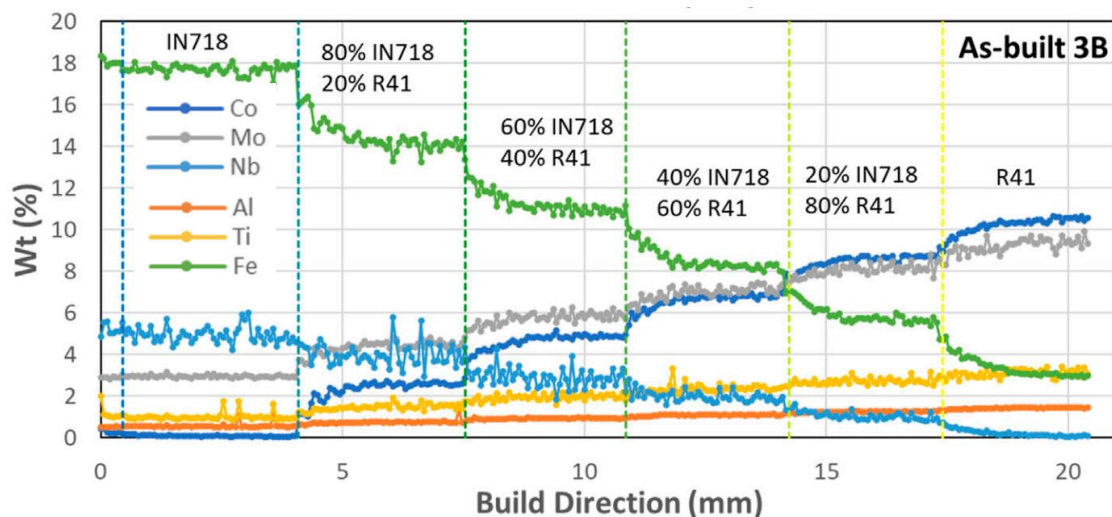
# Example: visualize live root system



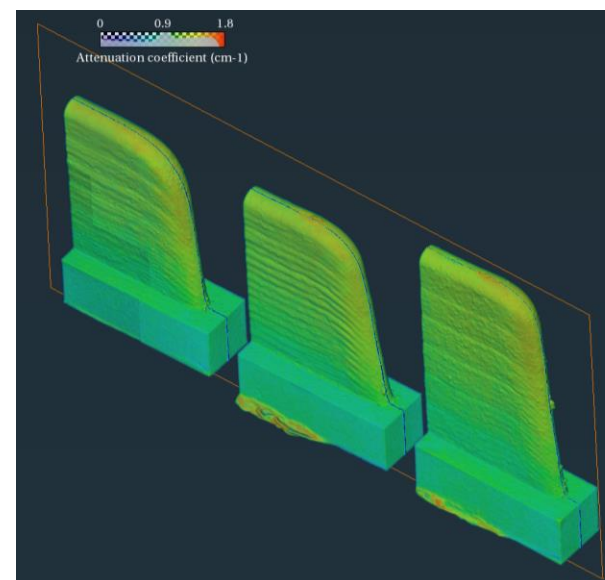
# Resolve the composition gradient in graded superalloy



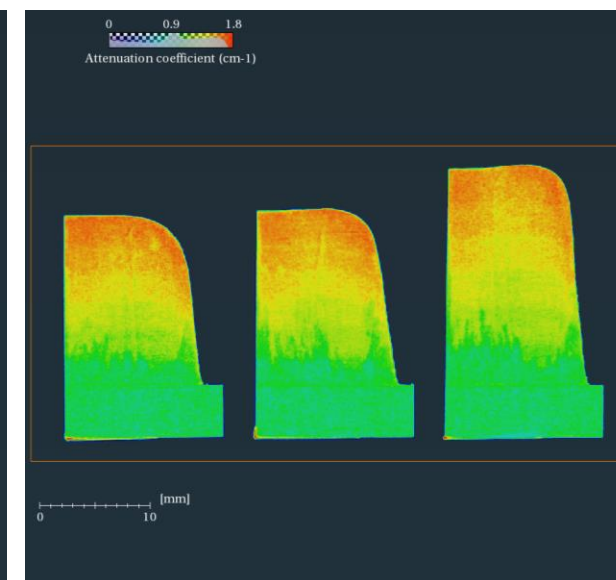
Transmission image



Huang S., Shen C., An K., Zhang Y., Spinelli I., Brennan M., Yu D., *Frontiers in Metals and Alloys*, 1, 1070562 (2022)

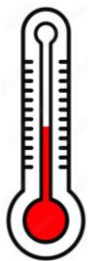
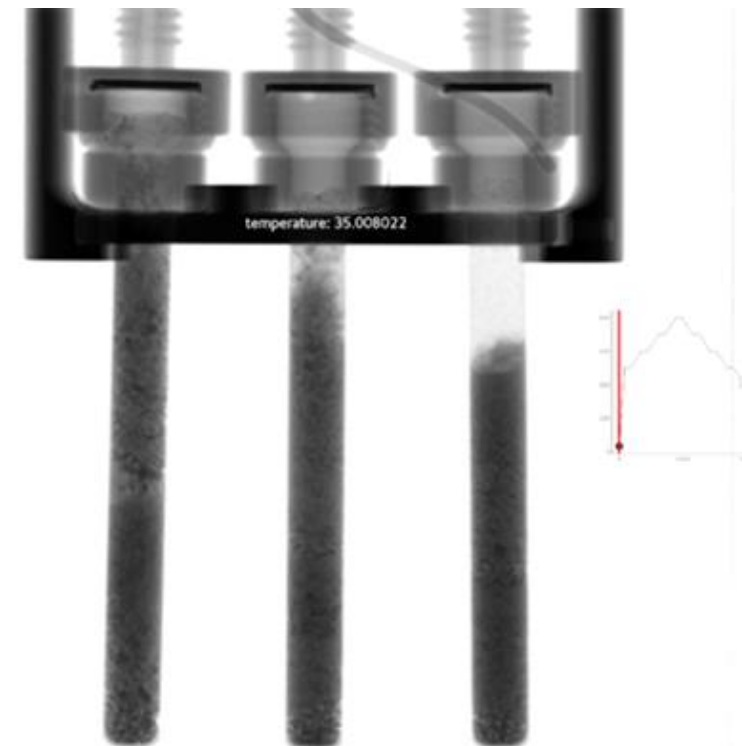
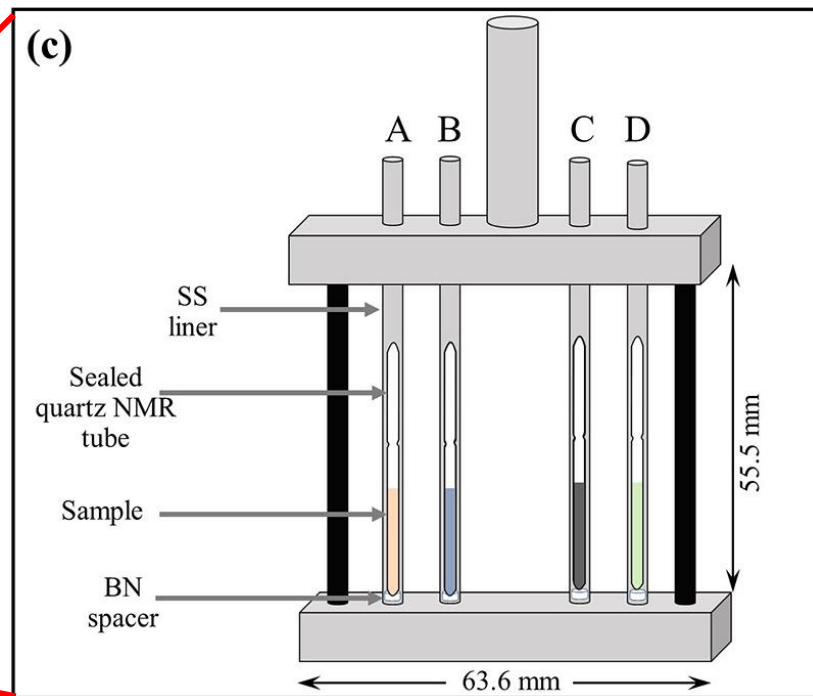
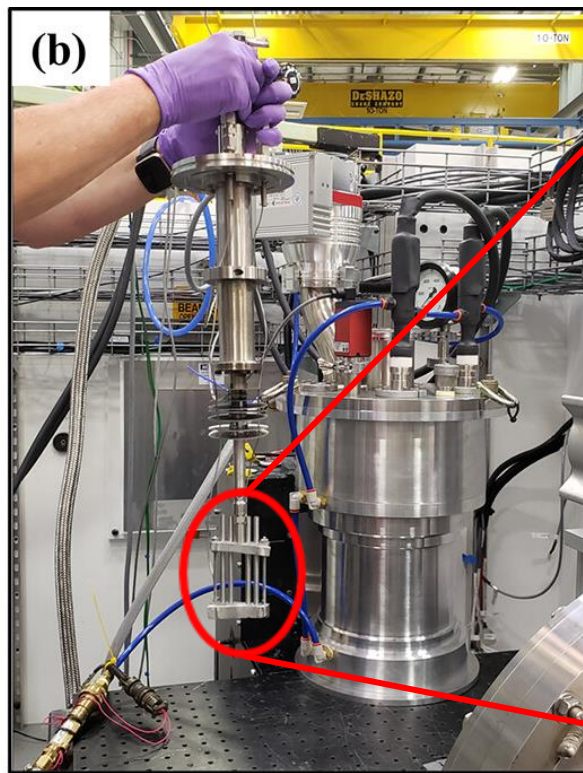


Reconstructed 3D volume (virtual slicing location in orange)



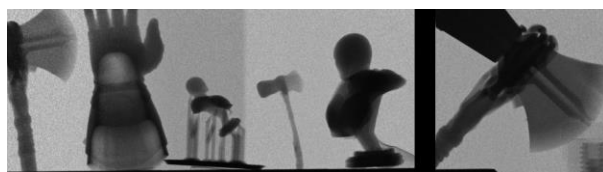
Cross-sectional view after virtually slicing

# Measures molten salt densities at MSR operating temperatures

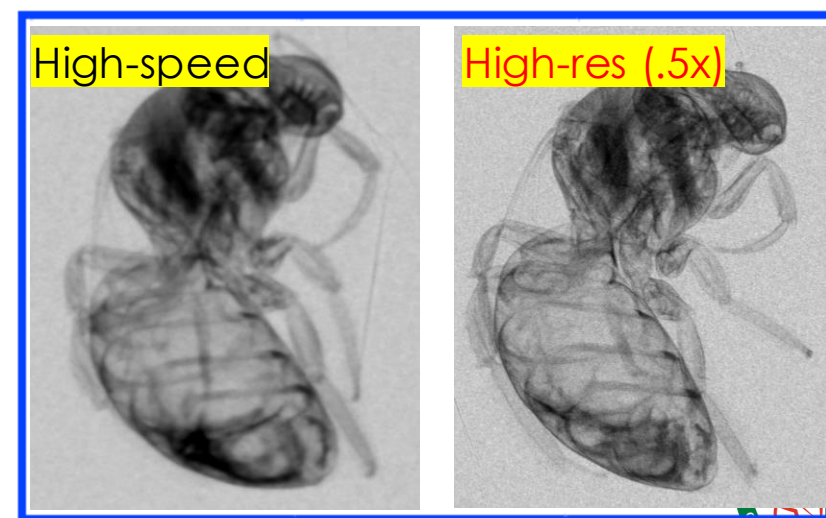
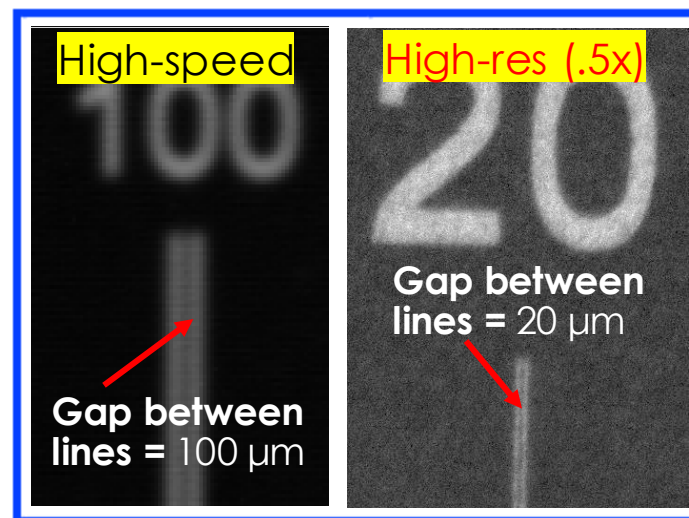


# Resolutions and FOVs

Type of detector	Field-of-view (FOV)	Pixel size ( $\mu\text{m}$ )	Highest spatial resolution ( $\mu\text{m}$ )	Typical acquisition time of 1 radiograph	Maximum speed @16 bit
High-res (1x)	36 x 24 mm <sup>2</sup>	3.8	10-15	900 s	1 image/second
High-res (.5x)	50 x 48 mm <sup>2</sup>	7.63	20-25	300 s	1 image/second
High-speed	88 x 88 mm <sup>2</sup>	43	~100	—	74 image/second
Balanced	88 x 88 mm <sup>2</sup>	16	~50	30-90 s	1 image/second



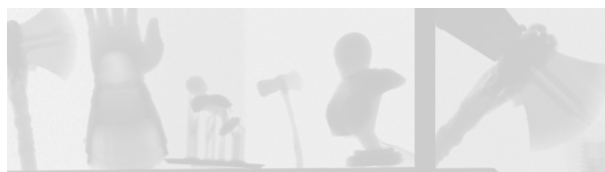
(Sample credit: George Williams)



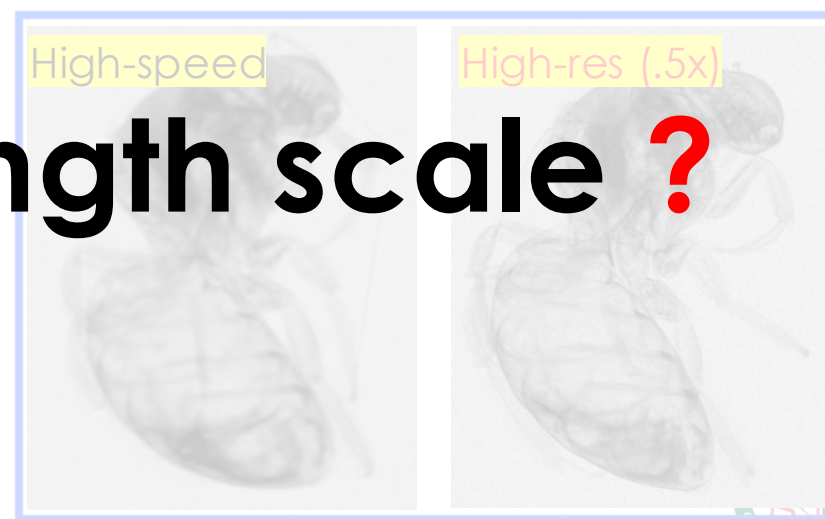
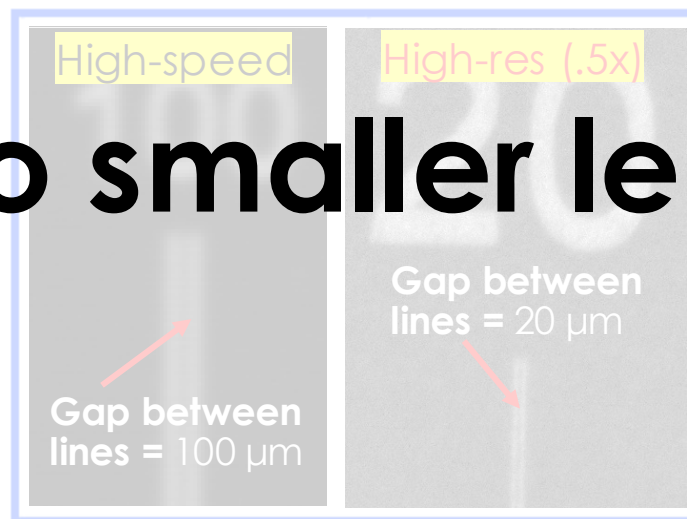
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High-speed	88 x 88 mm <sup>2</sup>	16	50	30 s	4 images/second
Balanced	88 x 88 mm <sup>2</sup>	16	50	30 s	1 image/second

**Transmission mode  
resolves micro features (10-100  $\mu\text{m}$ )  
in cm sized samples ✓**



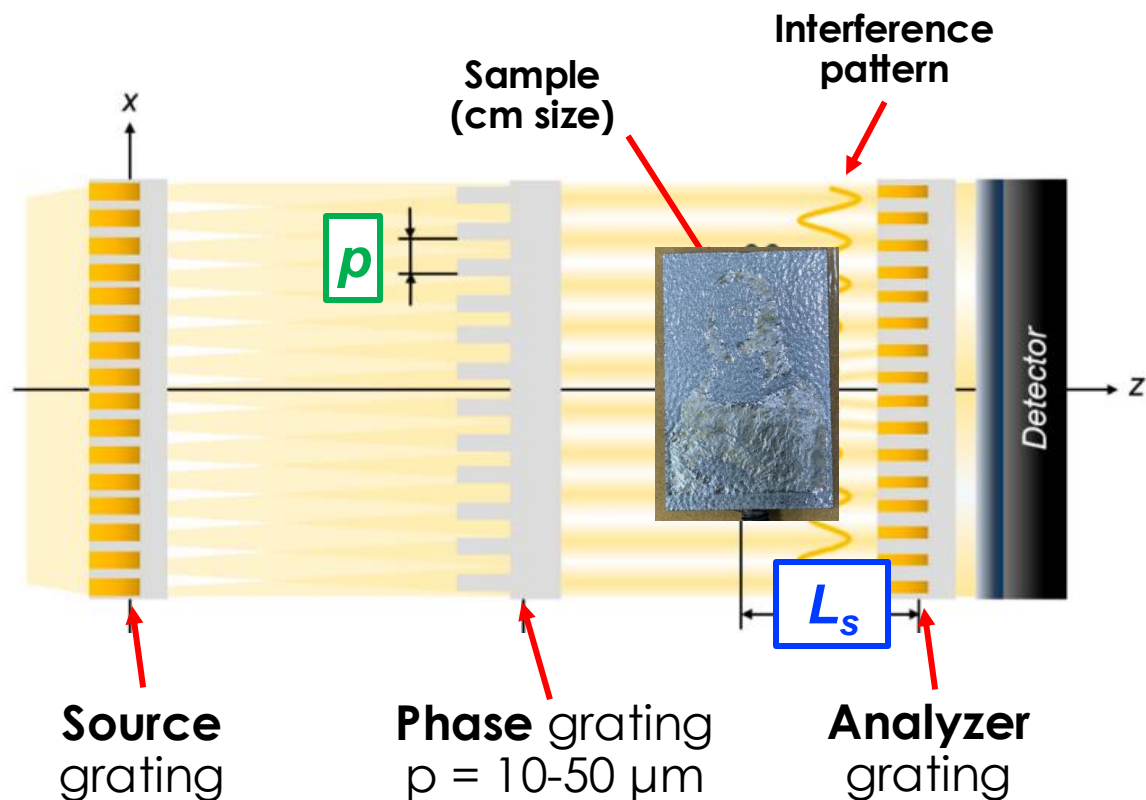
(Sample credit: George Williams)



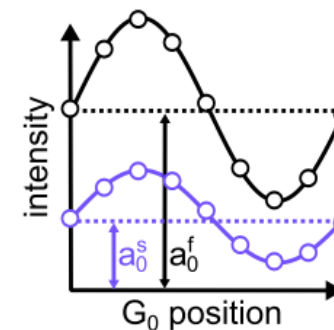
**Go down to smaller length scale ?**

# What is neutron grating interferometry (nGI)?

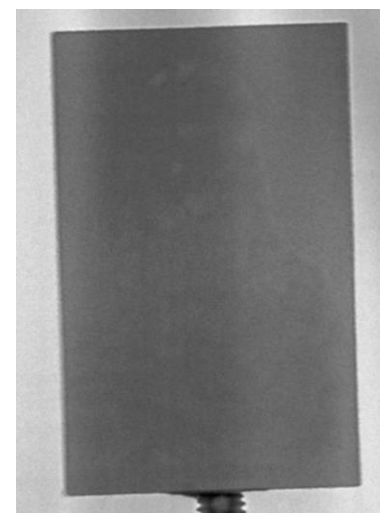
A neutron imaging instrumentation that enable the utilization the **wave properties of neutron**, to spatially resolve sub  $\mu\text{m}$  internal features



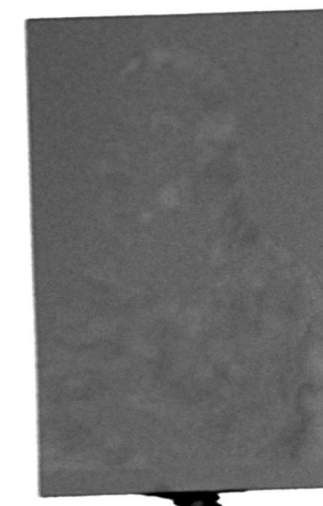
Y. Kim et al., *Applied Sciences* (2022).  
(Sample courtesy of Dr. Chris Fancher)



T. Reimann et al., *J. Applied Crystallography*. (2016)



Raw data resulted from a step-wise scan

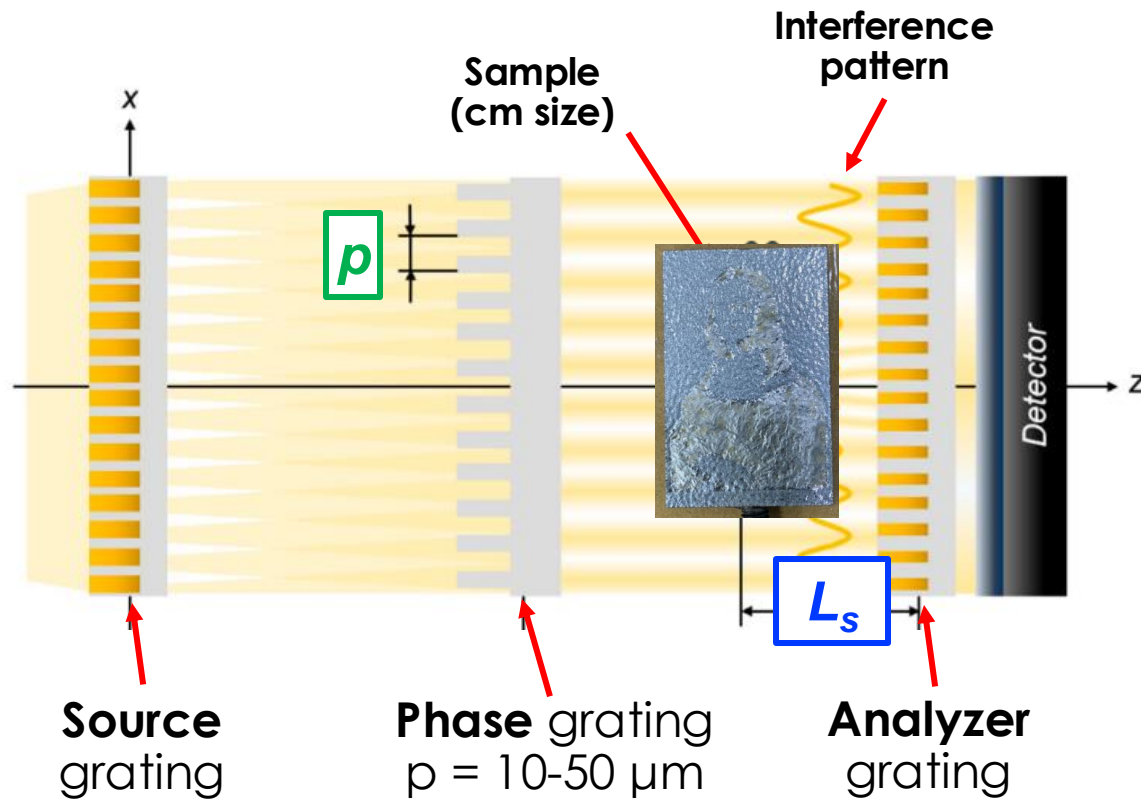


Transmission Image (TI)

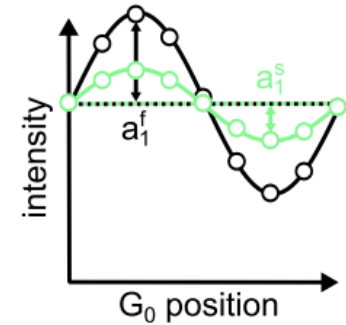


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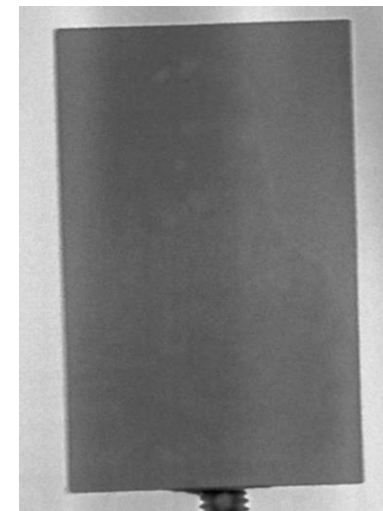
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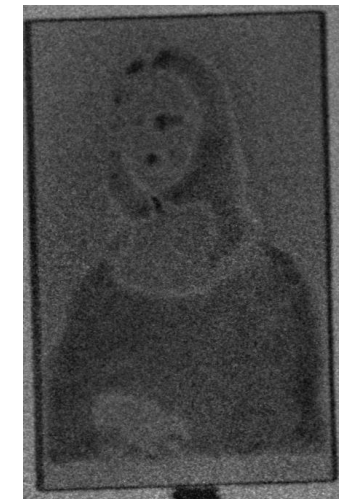
Y. Kim et al., *Applied Sciences* (2022).  
(Sample courtesy of Dr. Chris Fancher)



T. Reimann et al., *J. Applied Crystallography*. (2016)



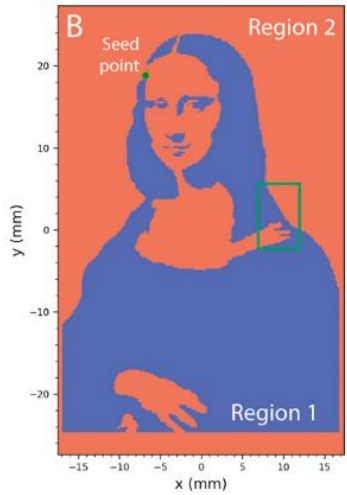
Raw data resulted from a step-wise scan



Dark Field Image (DFI)

# More about this sample along with the nGI results

Inconel



Two different cooling rate regions in an Inconel sample

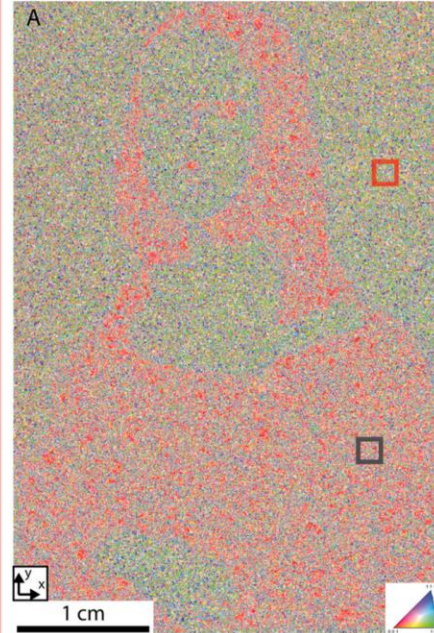
(Sample courtesy of Dr. Chris Fancher)

EBSD image is from Plotkowski et al., *Additive Manufacturing*. 46, 102092, (2021).

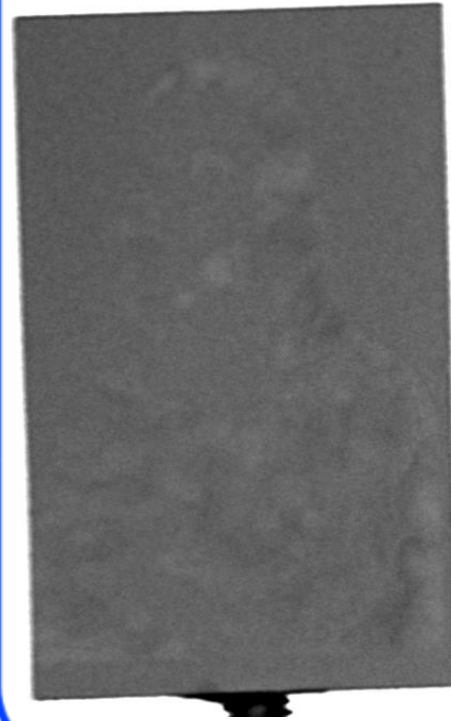
Photo



EBSD



Transmission (TI)

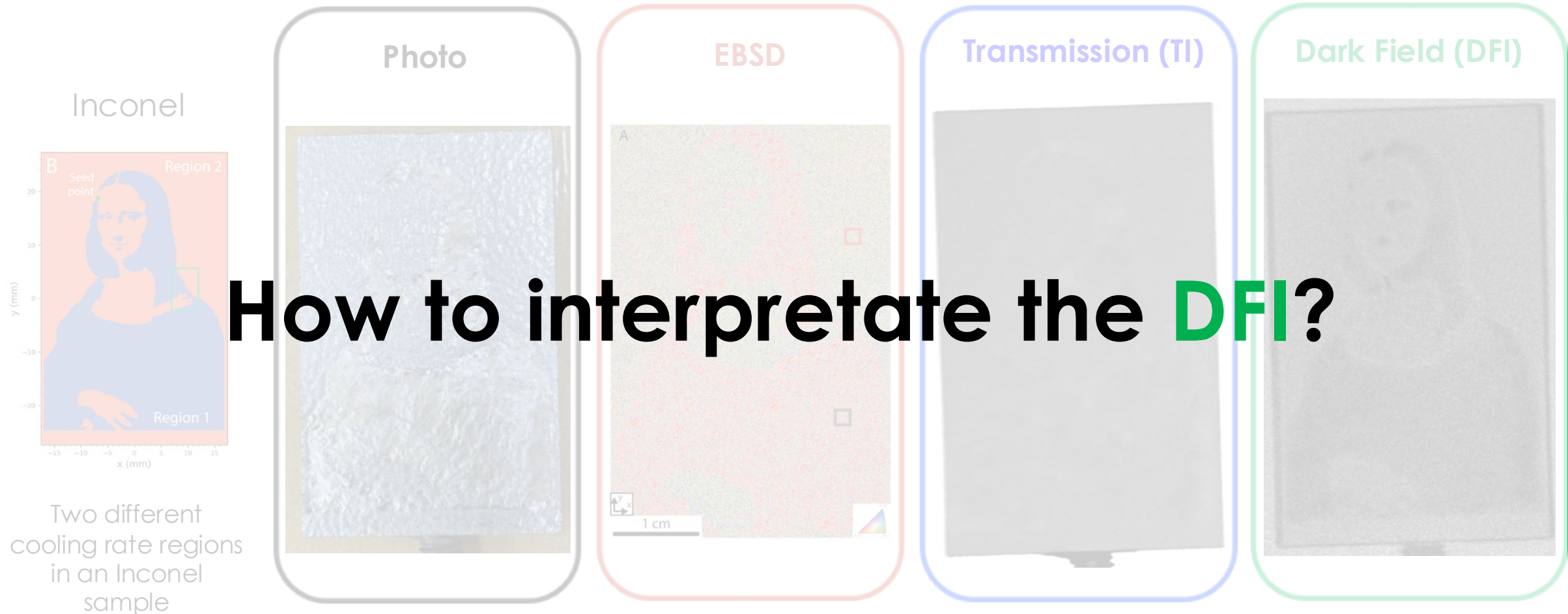


Dark Field (DFI)



Color relates to the SANS from features in certain sizes

# More about this sample along with the nGI results

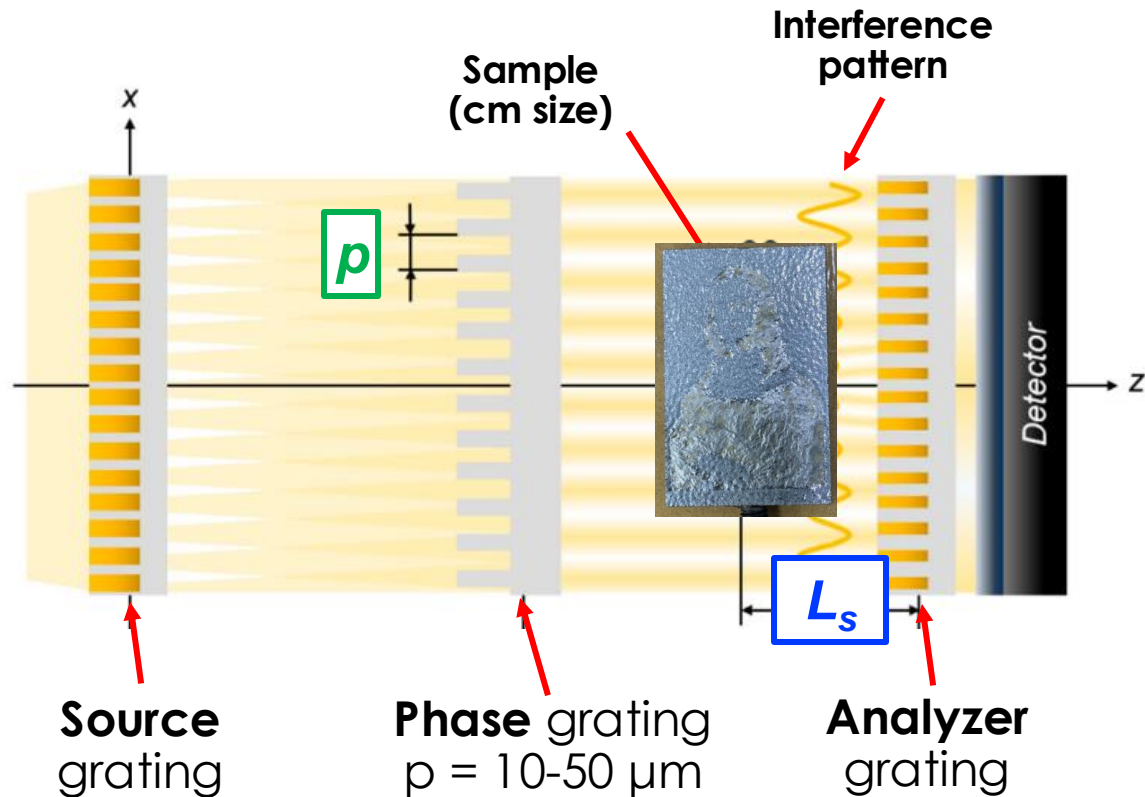


(Sample courtesy of Dr. Chris Fancher)

EBSD image is from Plotkowski et al., *Additive Manufacturing*. 46, 102092, (2021).

Color relates to the SANS from features in certain sizes

# Scan through various correlation lengths to understand the length scale



Autocorrelation length

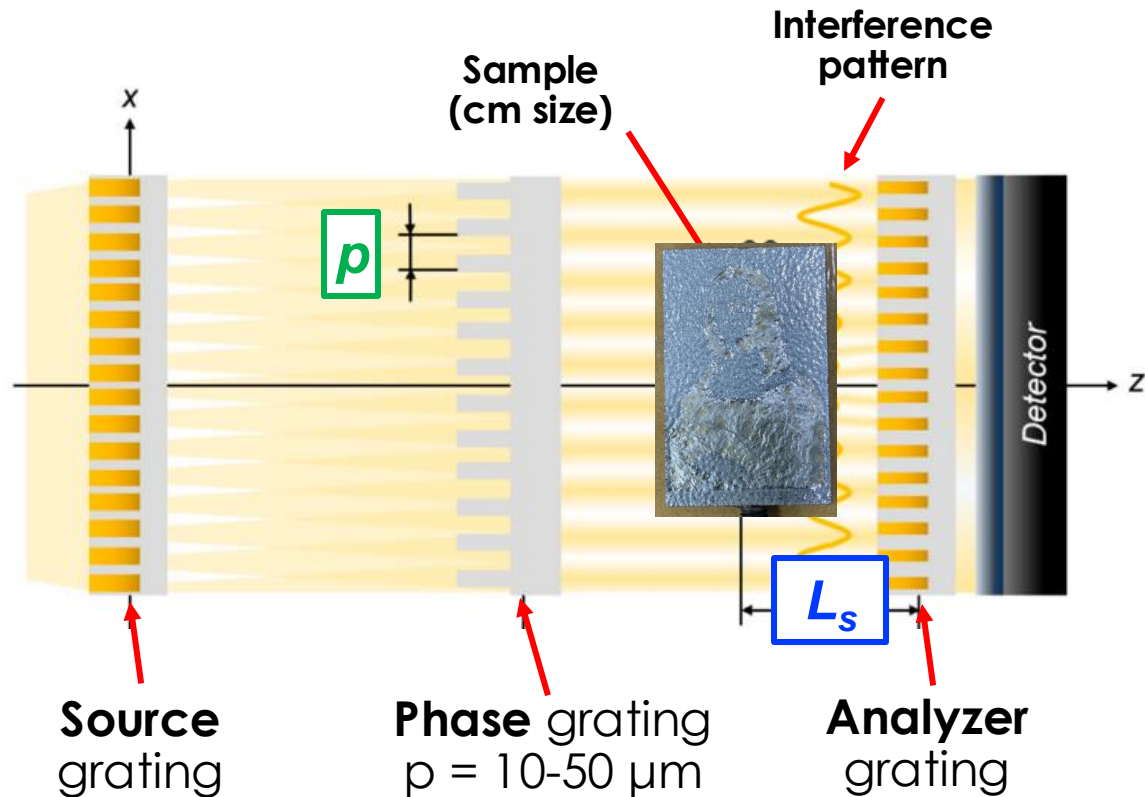
Neutron Wavelength

$$\xi = \lambda L_s / p$$

Y. Kim et al., *Applied Sciences* (2022).

(Sample courtesy of Dr. Chris Fancher)

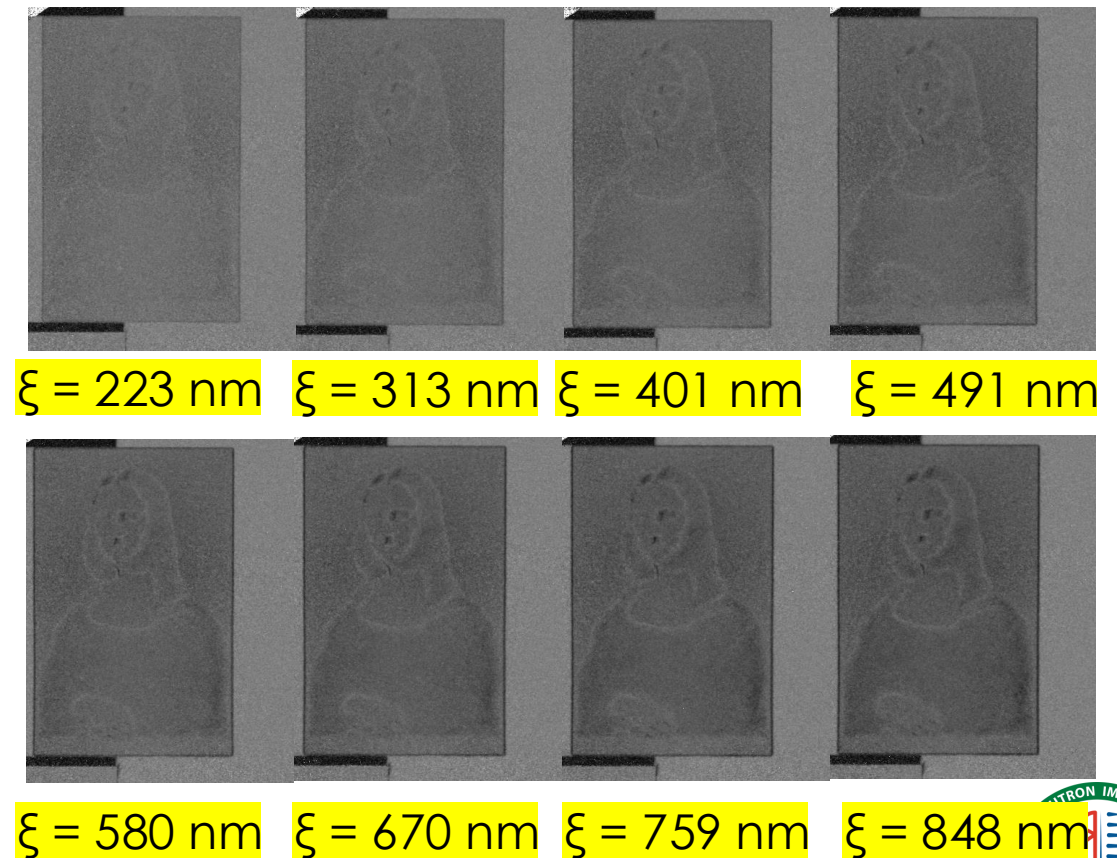
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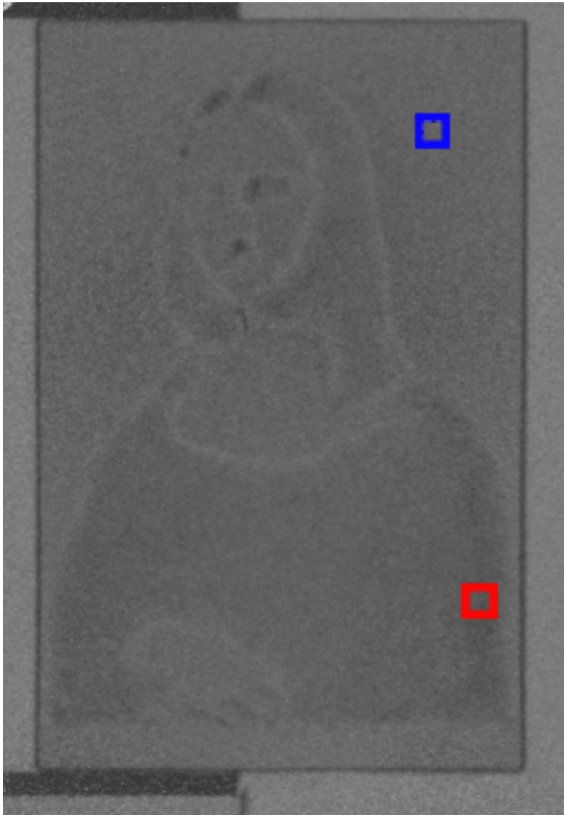
Y. Kim et al., *Applied Sciences* (2022).

(Sample courtesy of Dr. Chris Fancher)

Correlation length  $\xi = \lambda L_s / p$  Neutron Wavelength

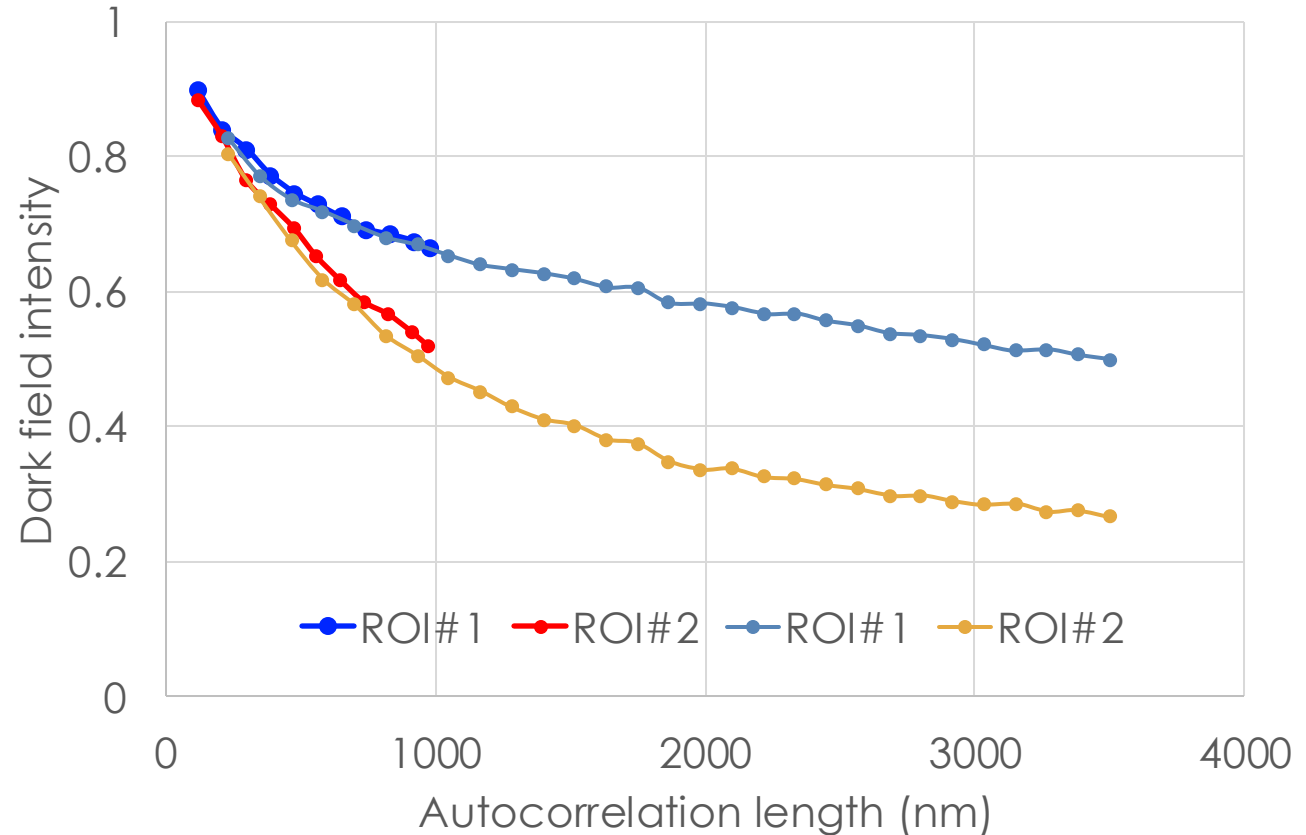


# Plotting the dark field intensity vs. $\xi$ in region-of-interest (ROI)



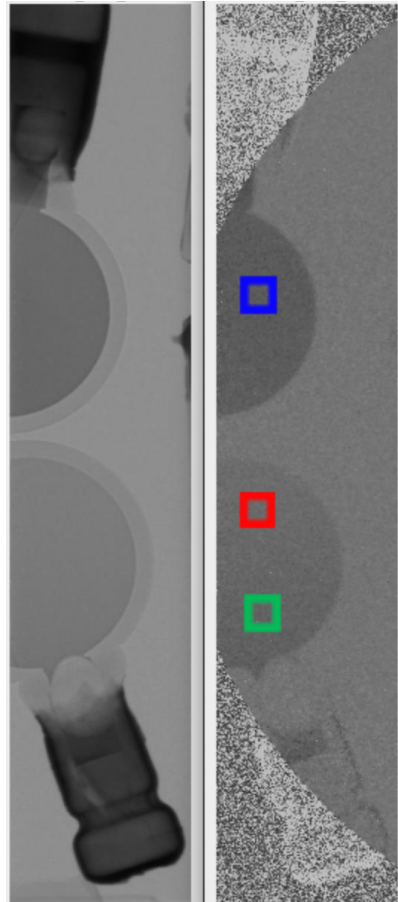
DFI

(Sample courtesy of Dr. Chris Fancher)



- Indicating different microstructures between selected ROIs

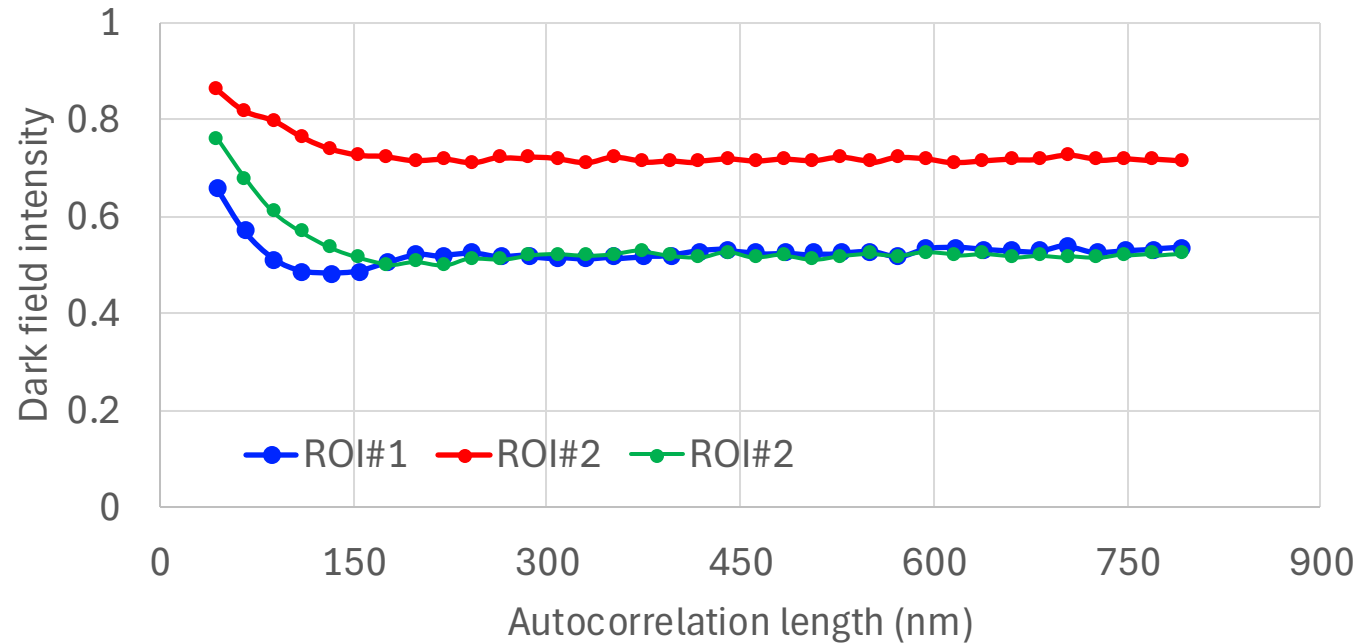
# Measurement of suspended PMMA spheres in solution as a calibration standard



TI

DFI

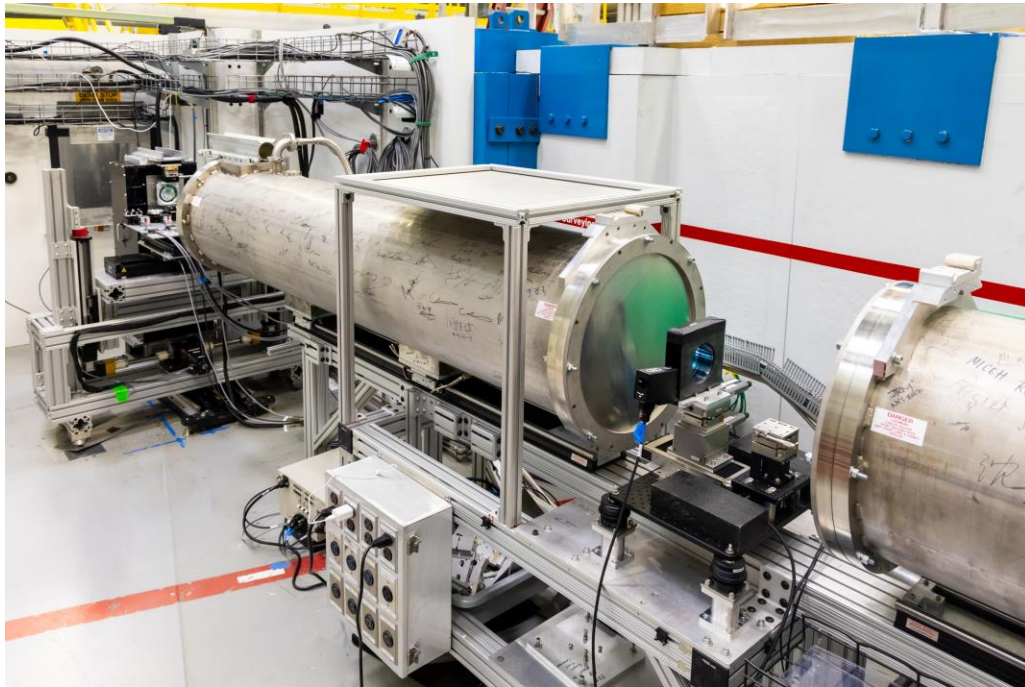
(Sample courtesy of Dr. Fankang Li)



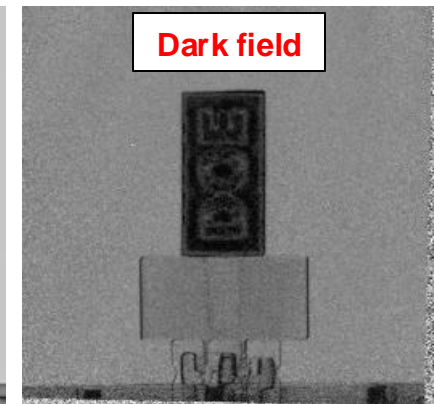
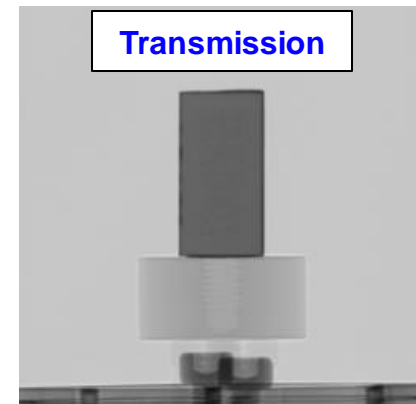
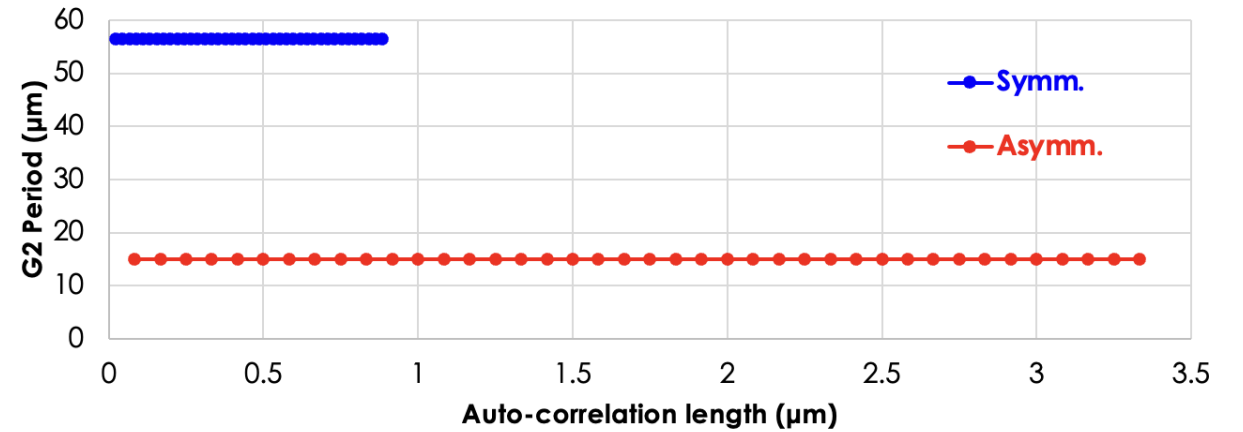
- The curves indicate the size of the PMMA spheres, which match well with the spec. (~100 nm in the top cell, ~150 nm in the bottom cell)
- Some settling observed in the bottom cell, resulted difference in number density of PMMA can be observed

# nGI capability at MARS

Two setups to cover ACL ranges from ~40 nm to ~3400 nm



**ACL Coverage for 2.5 Å**  
(Max. sample distance = 20 cm)



(Sample courtesy of R. Dehoff)



# Outline

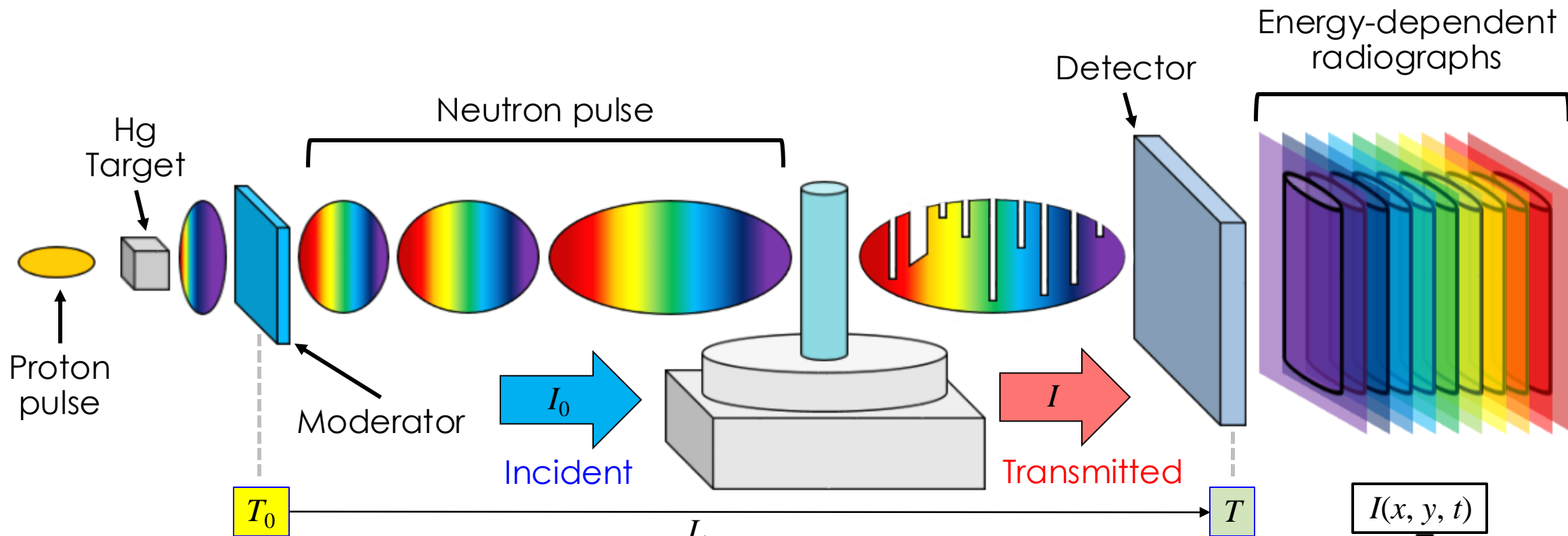
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- Scientific programming

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# Imaging at a pulsed source (SNS)

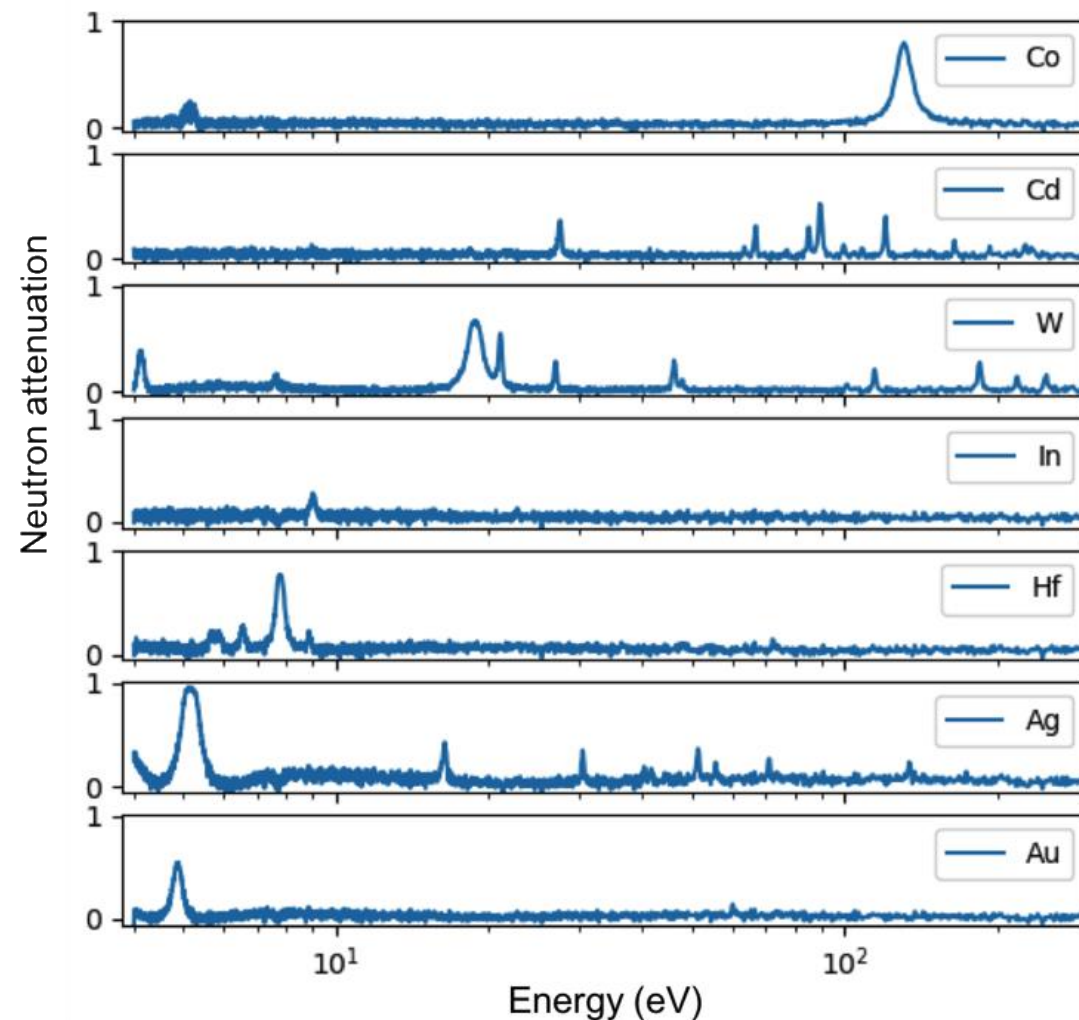
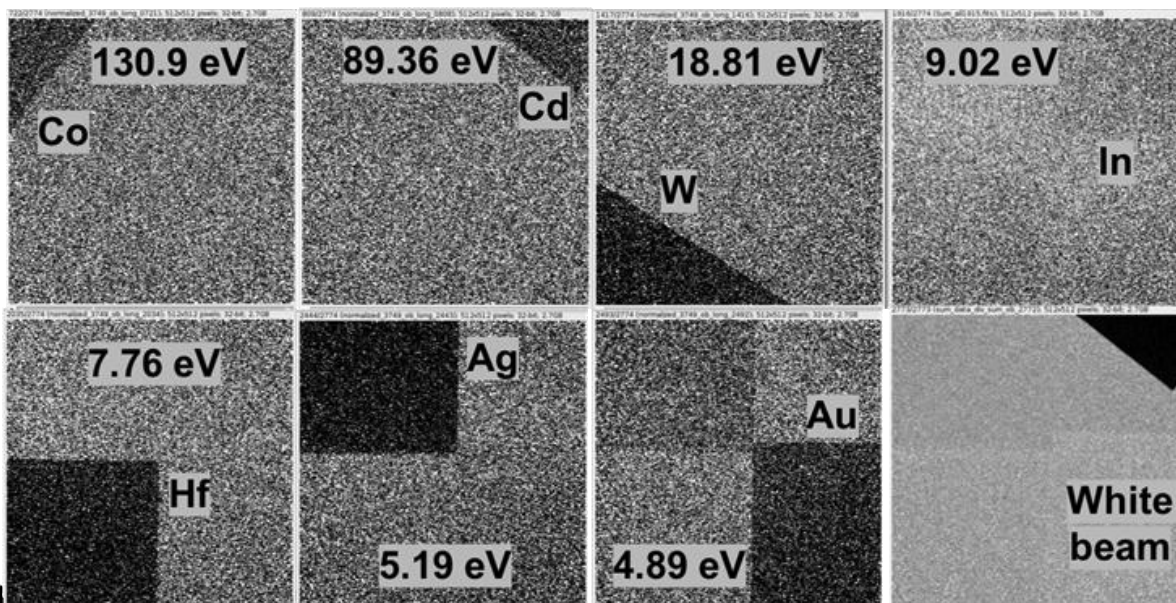
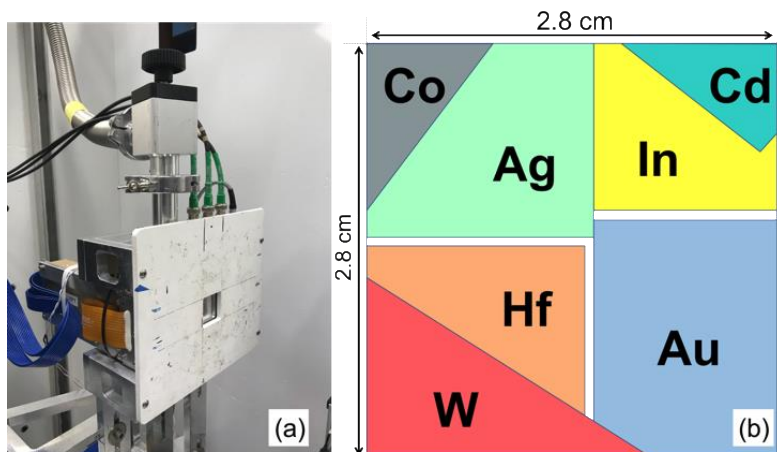


Courtesy of Y. Zhang, ORNL

$$I(\lambda) = I_0(\lambda)e^{-\mu(\lambda)x} \quad \mu(\lambda) = \sigma_t(\lambda) \frac{\rho N_A}{M}$$

$I(x, y, t)$   
 $\downarrow$   
 $I(x, y, \lambda)$   
 or  
 $I(x, y, E)$

# Higher energy neutrons can also be used for imaging (neutrons of energies higher than 1 eV): Resonance Imaging

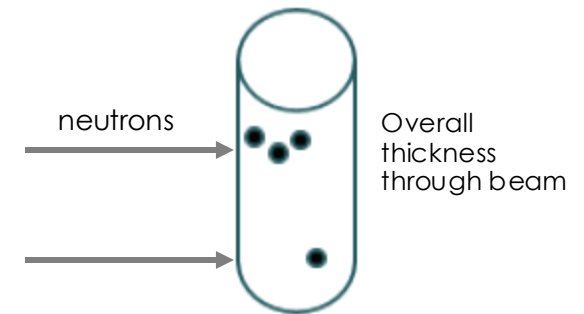


Zhang Y., Myhre K.G., Bilheux H.Z., Tremsin A.S., Johnson J.A., Bilheux J., Miskowicz A., Hunt R.D., Santodonato L., Molaison J.J., "[Neutron Resonance Radiography and Application to Nuclear Fuel Materials](#)", *Transactions of the American Nuclear Society*, (2018).

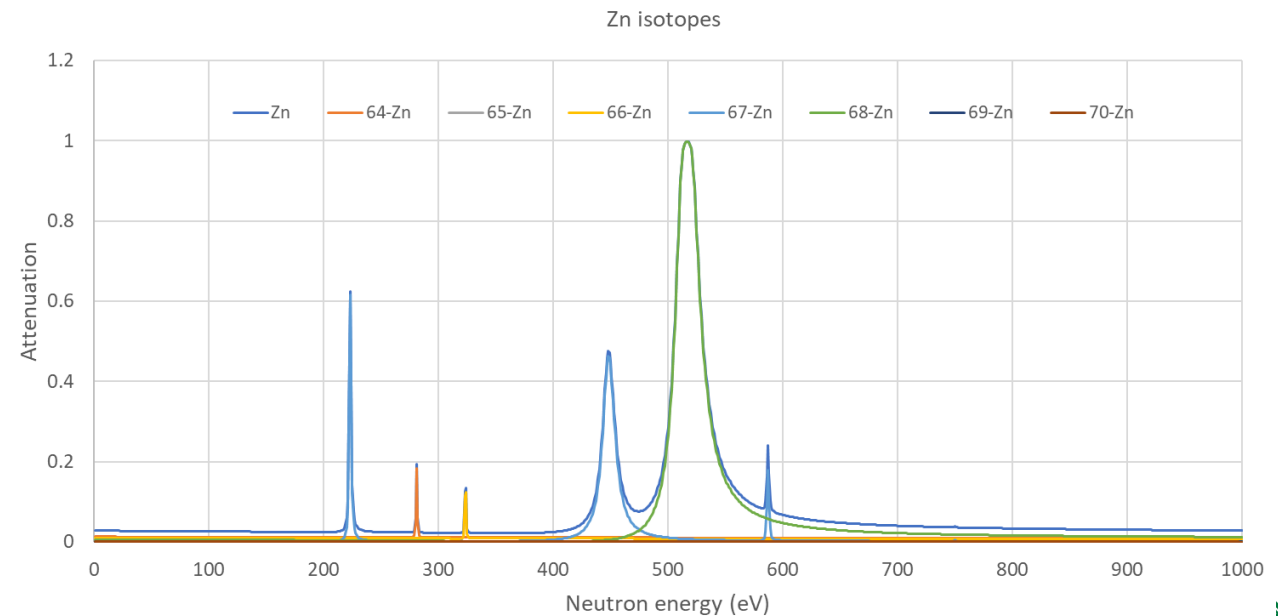
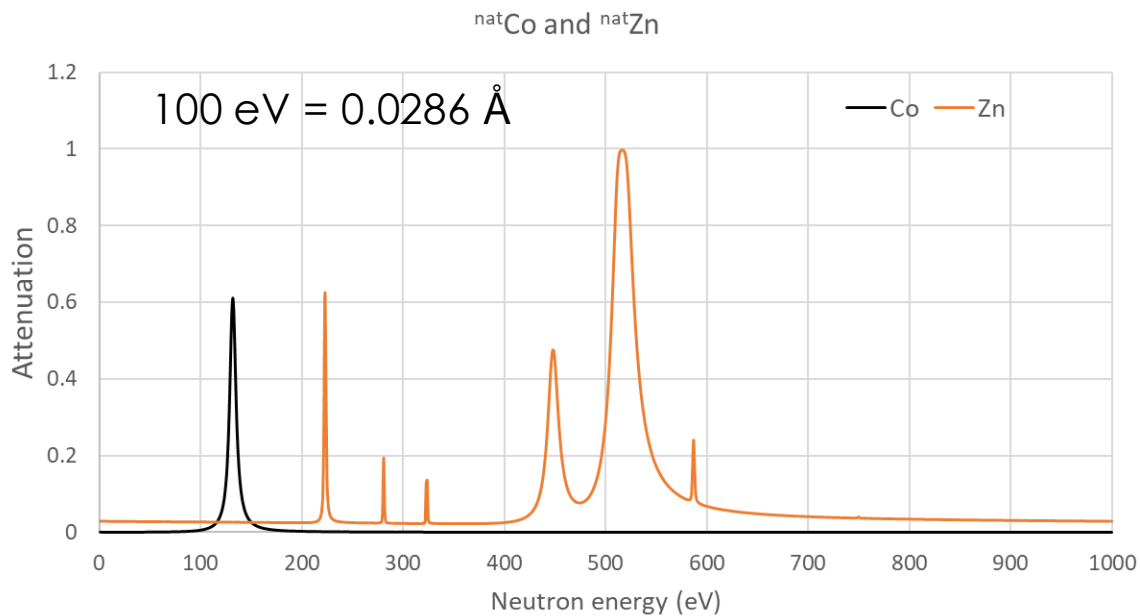
# Resonance imaging ( $> 1 \text{ eV}$ or $< 0.286 \text{ \AA}$ ): preparing your experiment

- Soil surveys, contaminants in soil, etc.:

- transmission through 0.01 mm thickness of  $^{nat}\text{Co}$  (between 1 and 5  $\text{\AA}$ ) = 99.5 %
- transmission through 1 mm thickness of  $^{nat}\text{Zn}$  (between 1 and 5  $\text{\AA}$ ) = 96.4 %

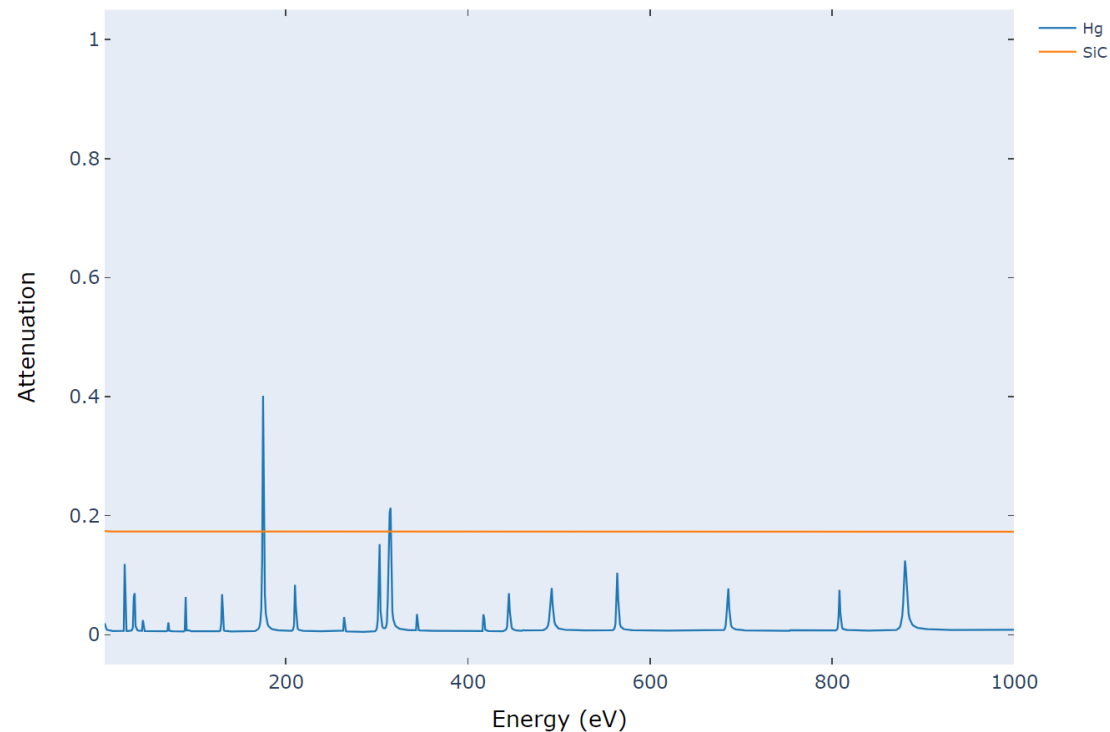


## Simulated resonance for elements of interest(\*)



# Resonance imaging: preparing your experiment (cont'd)

- Hg contamination in soil
  - Assumptions: 0.1 mm Hg ( $13.6 \text{ g/cm}^3$ ) + 12.5 mm SiC (with  $1.5 \text{ g/cm}^3$ )
    - Transmission (1 and 5 Å) = 66.4 %



Resonance peaks plotted with:

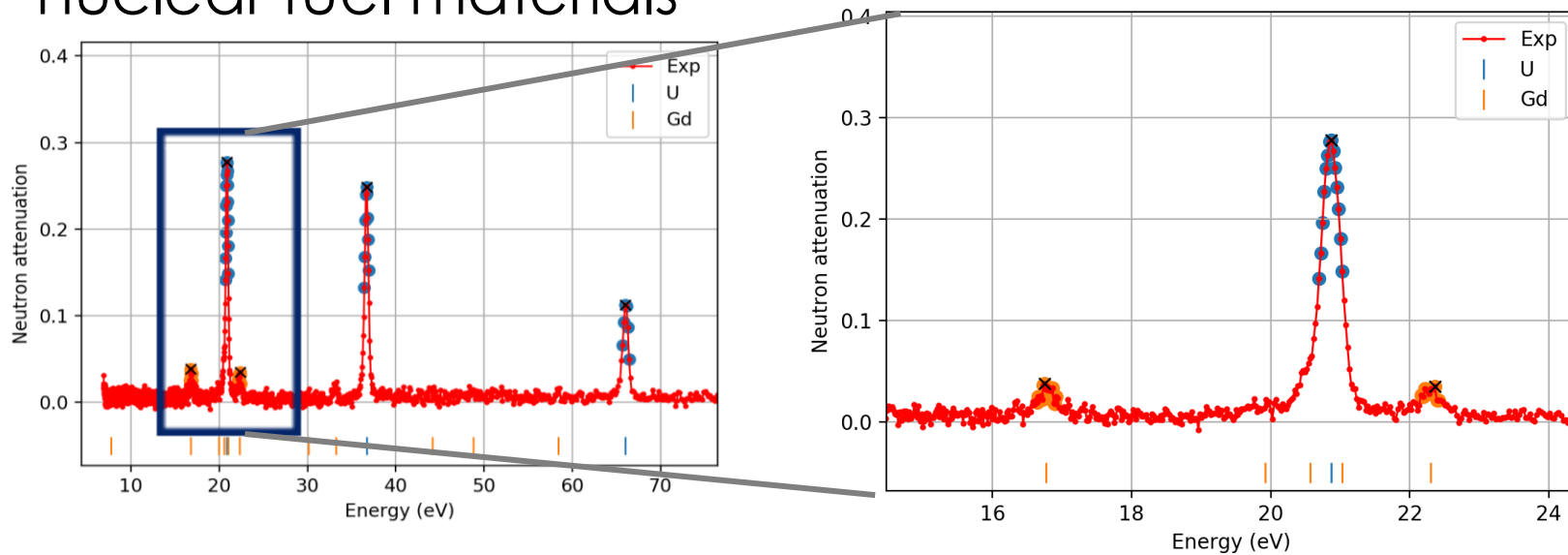
iNEUIT (*"I knew it"*)



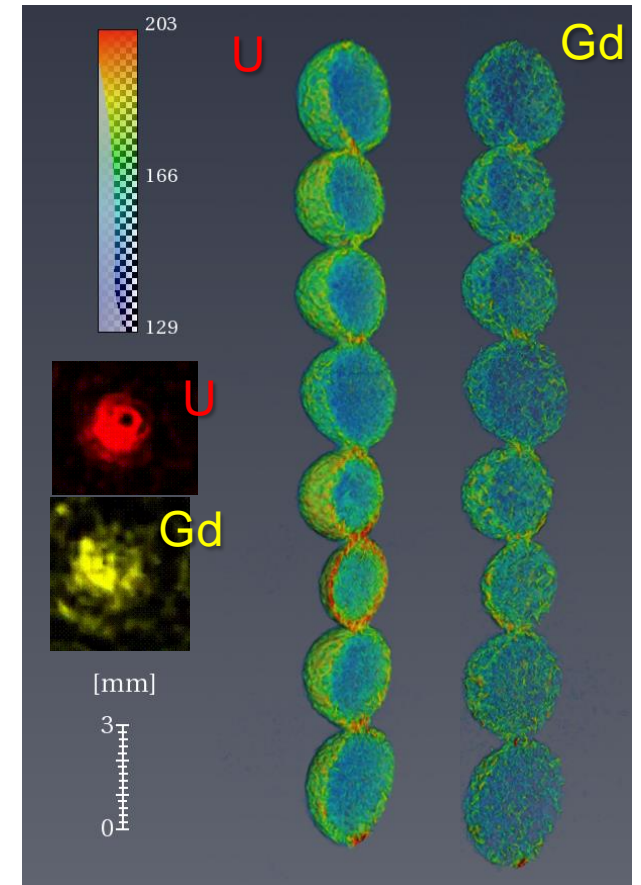
iNEUtron Imaging Toolbox

# Using epithermal neutrons (energy > 1 eV), resonance imaging can map the isotopic content in advanced nuclear fuel materials in 3D

- Distribution of elements drive the performance of the novel advanced nuclear fuel materials

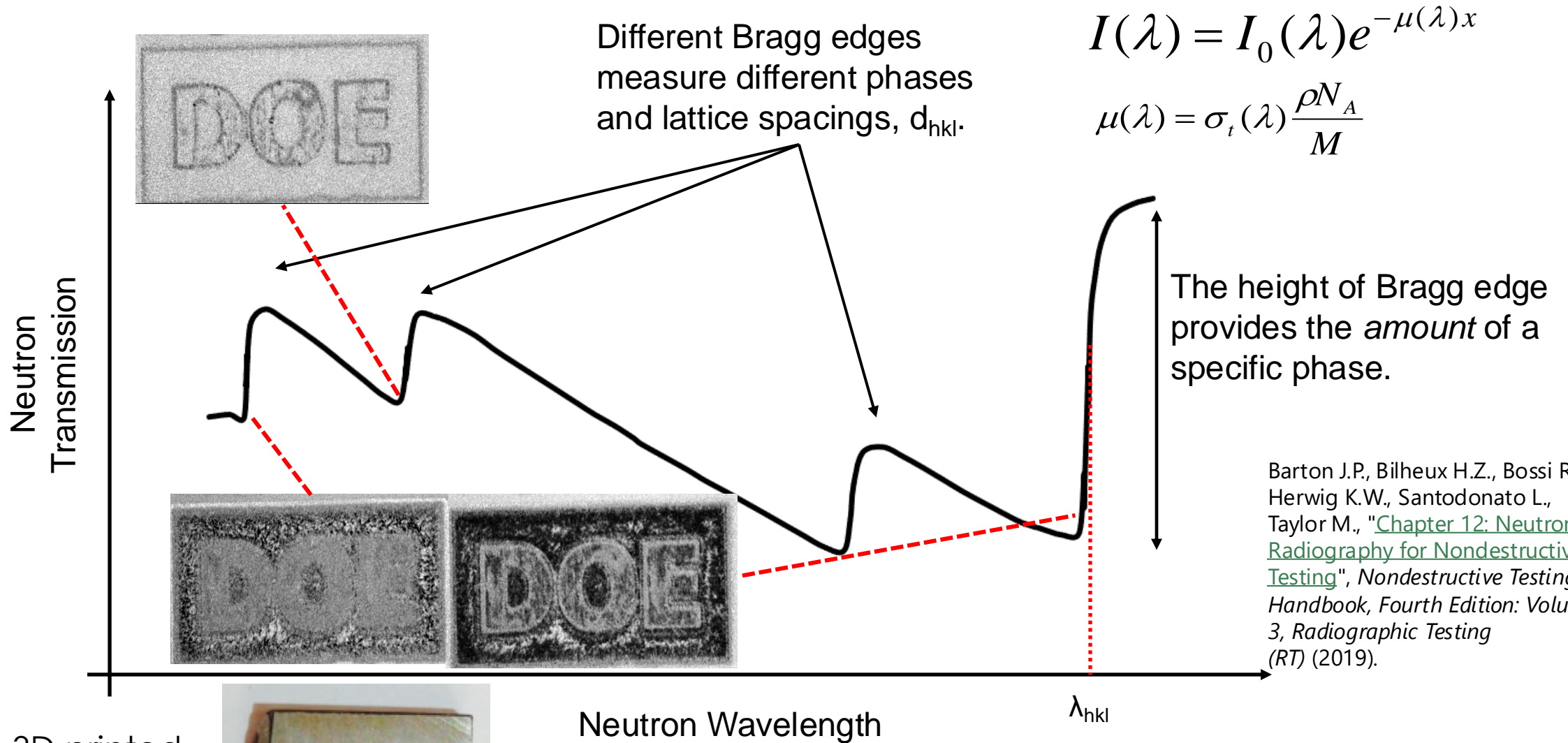


- Quantitative analysis is being developed using in-house open-source Python package (ResoFit)



Myhre K.G., Zhang Y., Bilheux H.Z., Johnson J.A., Bilheux J., Miskowiec A., Hunt R.D., "Nondestructive Tomographic Mapping of Uranium and Gadolinium Using Energy-Resolved Neutron Imaging", *Transactions of the American Nuclear Society*, (2018).

# Bragg edge imaging: how does it work?



Barton J.P., Bilheux H.Z., Bossi R., Herwig K.W., Santodonato L., Taylor M., "[Chapter 12: Neutron Radiography for Nondestructive Testing](#)", *Nondestructive Testing Handbook, Fourth Edition: Volume 3, Radiographic Testing (RT)* (2019).

3D printed Inconel 718



1 cm



The position of the Bragg edge,  $\lambda_{hkl} = 2 d_{hkl}$ , is a measure of the *strain* in the sample

# Principle of Bragg edge Transmission

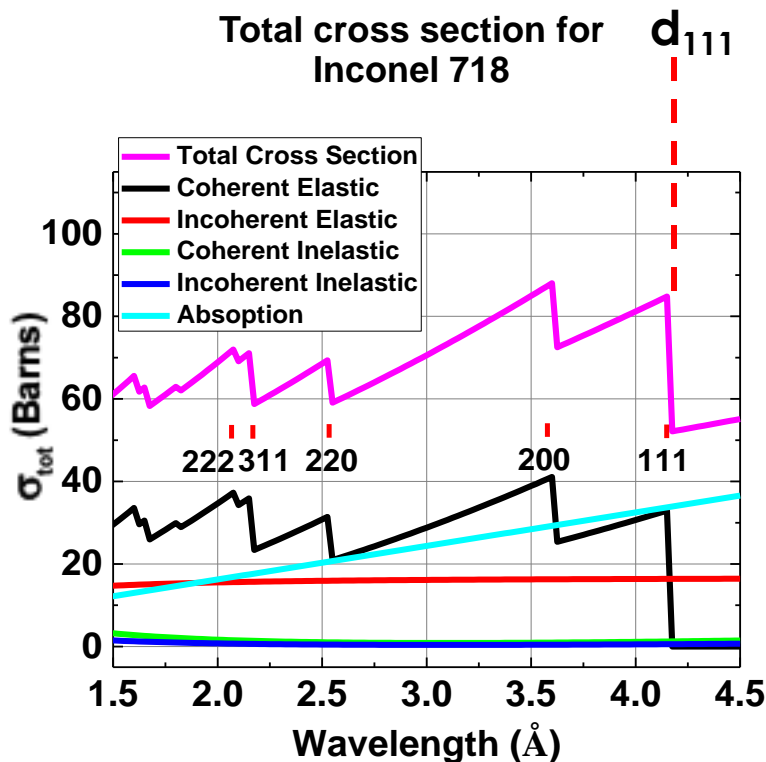
- ✓ Utilizes thermal and cold neutrons (approximately between 1 and 10 Å)
- ✓ Obeys Bragg's Law  $\lambda_{hkl} = 2d_{hkl} \sin \theta_{hkl}$  simplifies:  $\lambda_{hkl} = 2d_{hkl}$

$$\sigma_{Bragg}(\lambda) = \frac{\lambda^2}{2V_0} \sum_{hkl}^{2d_{hkl} > \lambda} |F_{hkl}|^2 d_{hkl} P(\alpha_{\vec{h}}(\lambda)) E_{hkl}(\lambda, F_{hkl})$$

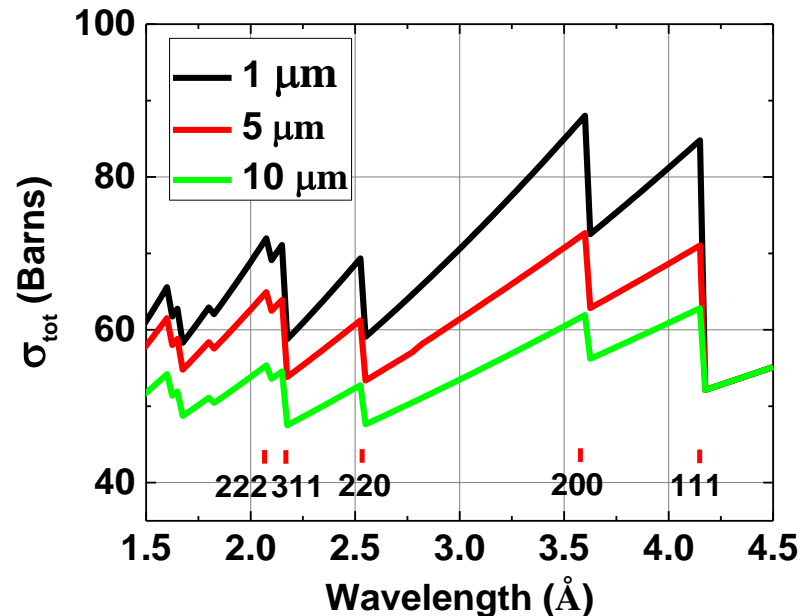
March-Dollase model     Sabine's primary extinction model

$V_0$ : volume of unit cell  
 $F_{hkl}$ : Structure factor including Debye-Waller factor

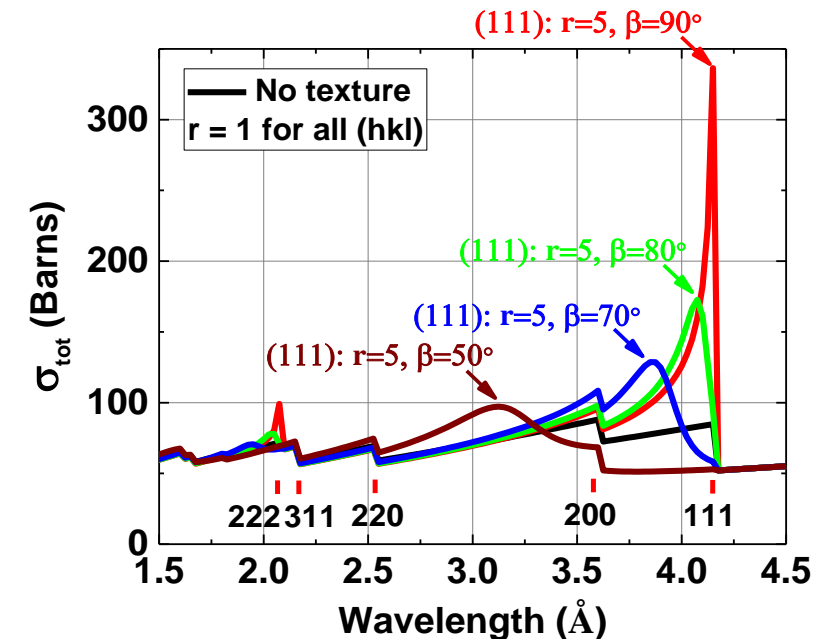
Total cross section for Inconel 718



Crystallite size effect ( $E_{hkl}$ )

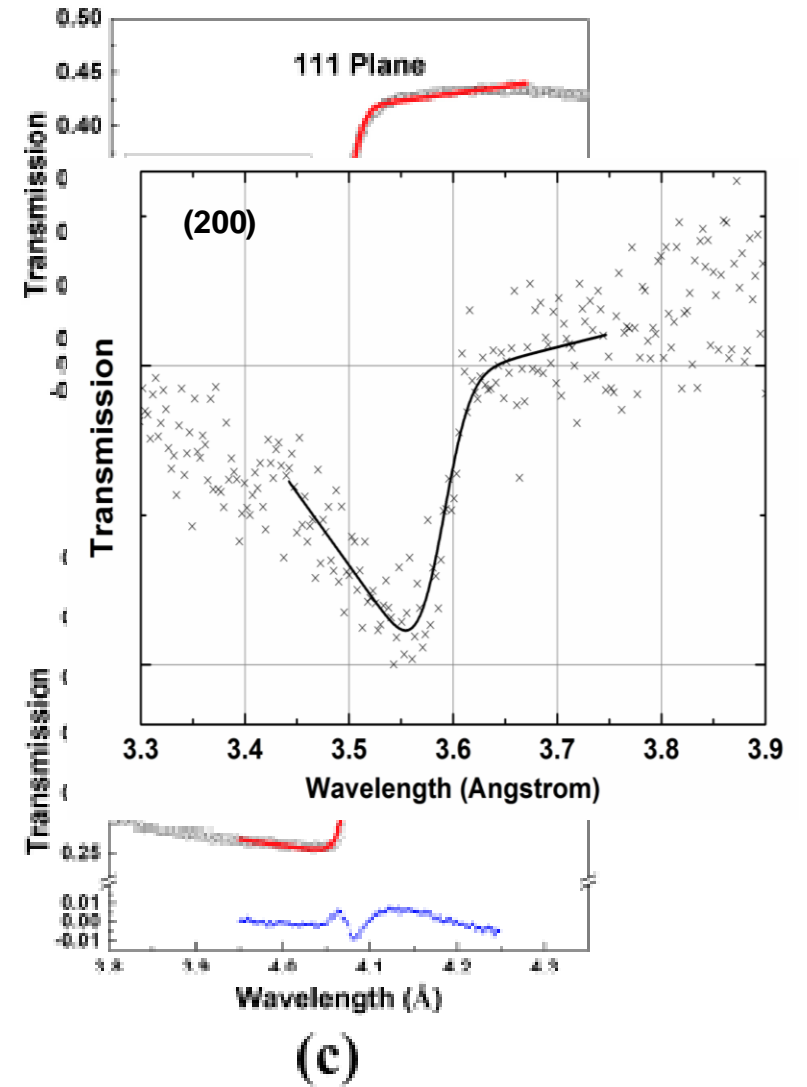
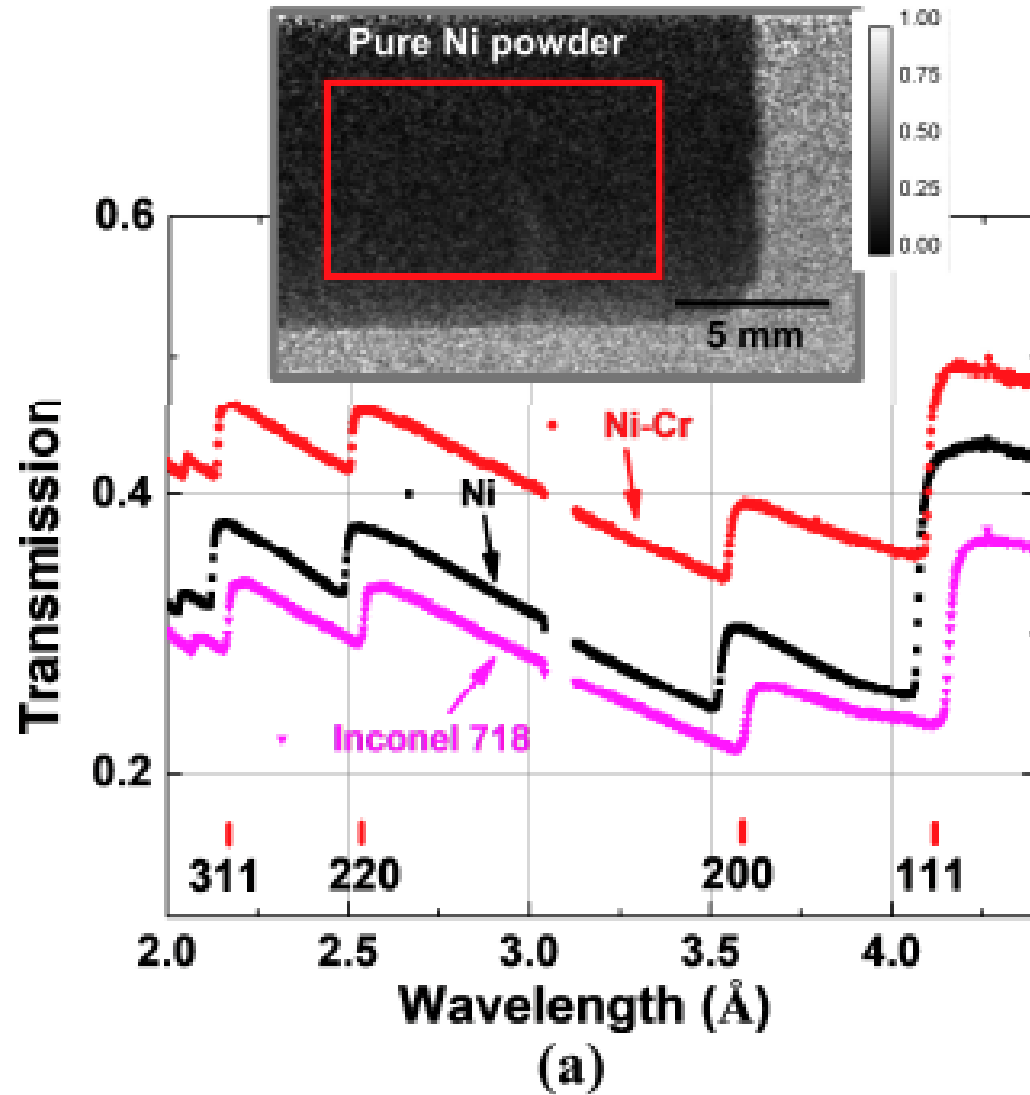


Crystallite orientation effect ( $P(\alpha_{\vec{h}}(\lambda))$ ):  $r$  and  $\beta$ )



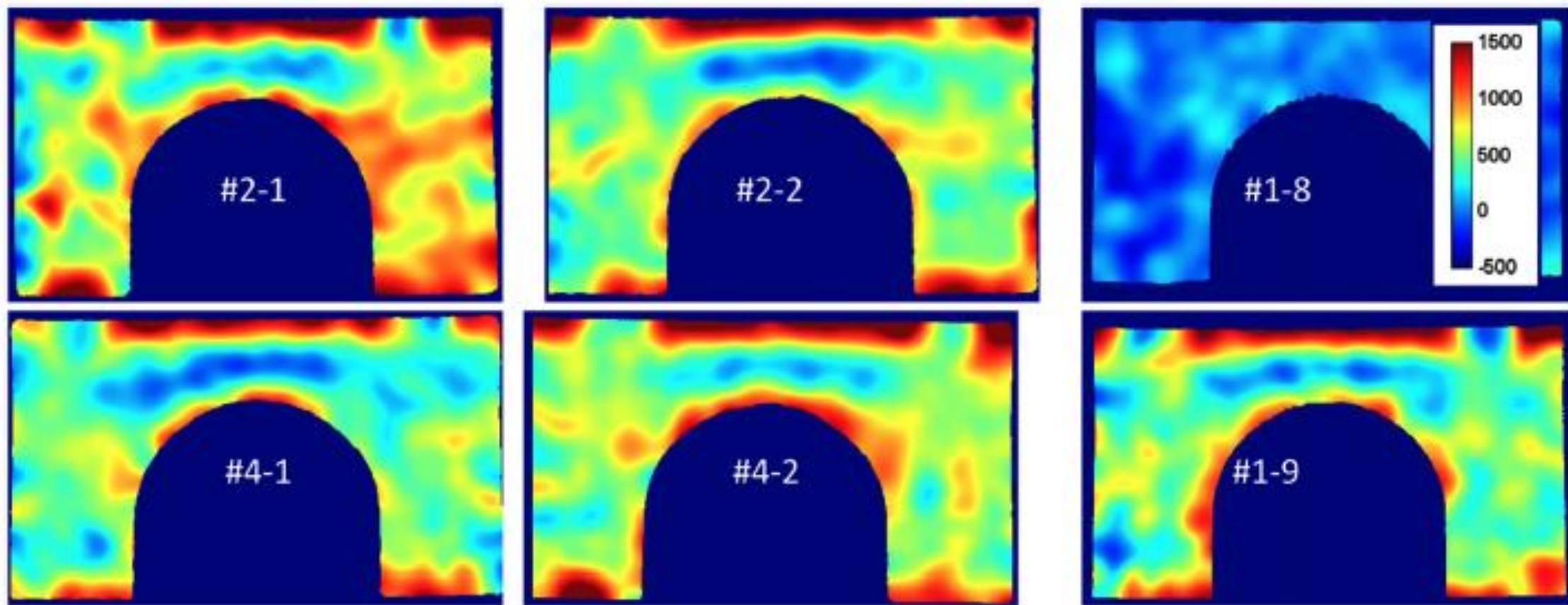


# The perfect case study: powders



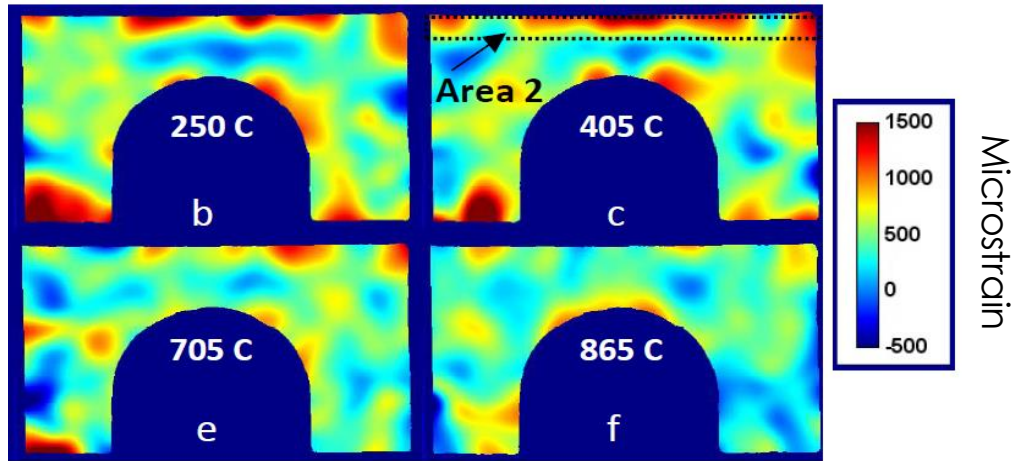
Song G., Lin J.Y., Bilheux J., Xie Q., Santodonato L., Molaison J.J., Skorpenske H.D., dos Santos A.M., Tulk C.A., An K., Stoica A.D., Kirka M.M., Dehoff R.R., Tremsin A.S., Bunn J.R., Sochalski-Kolbus L.M., Bilheux H.Z., ["Characterization of Crystallographic Structures Using Bragg-Edge Neutron Imaging at the Spallation Neutron Source"](#), *Journal of Imaging*, **3**, 4, 65 (2017).

# Materials Behavior: Monitoring residual strain relaxation and preferred grain orientation of additively manufactured Inconel 625 by in-situ neutron imaging

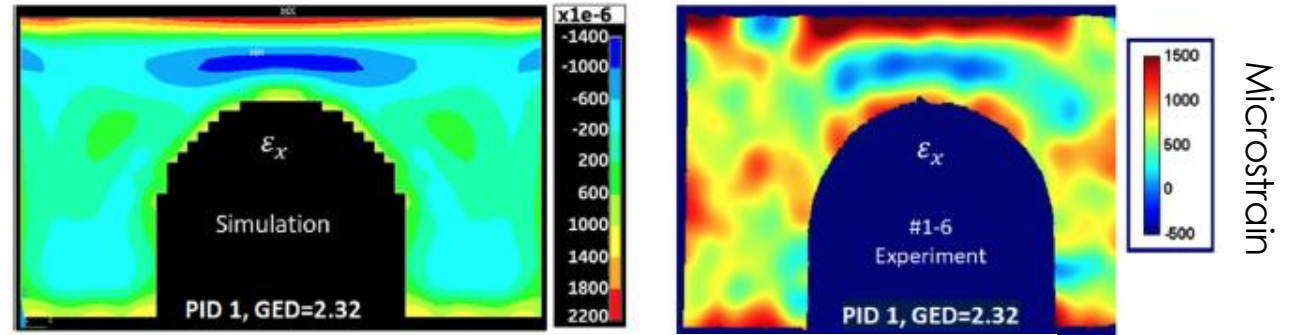
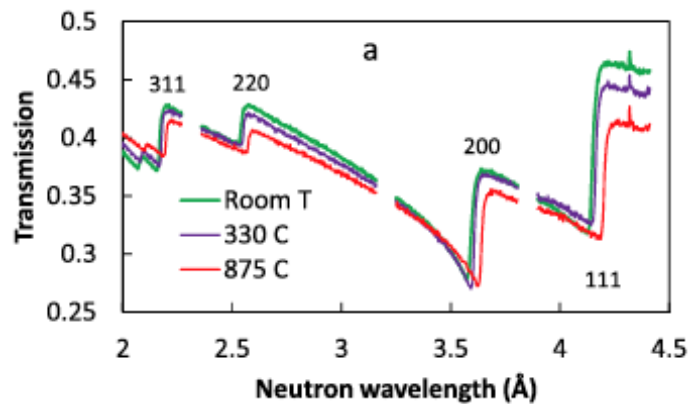


**Fig. 8.** Strain distribution (in microstrain) at the (111) Bragg edge measured at room temperature along the sample thickness direction X. SNAP beamline. The image integration time was about 2 h at SNAP.  $\lambda_0$  value is taken from the annealed sample #1-8 (average across the entire sample). The legend indicates the strain values in microstrain.

# Engineered Materials: Monitoring residual strain relaxation and preferred grain orientation of additively manufactured Inconel 625 by in-situ neutron imaging (10 min measurements)



AM Inconel 625 strain evolution as a function of temperature



Modeled and experimental results.

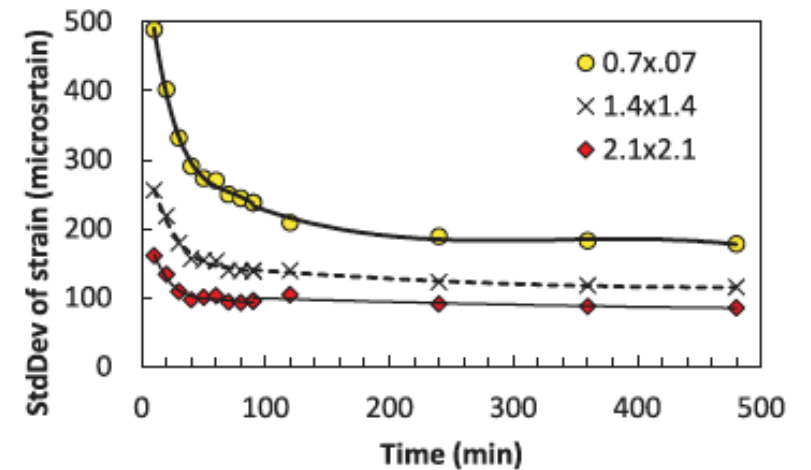
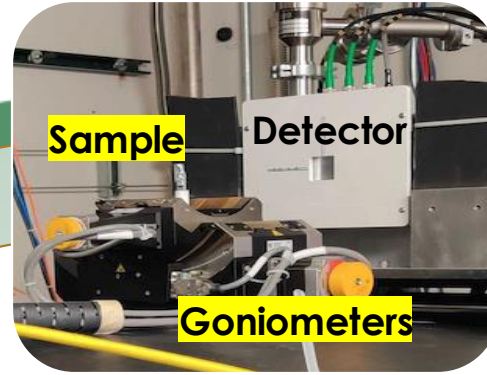
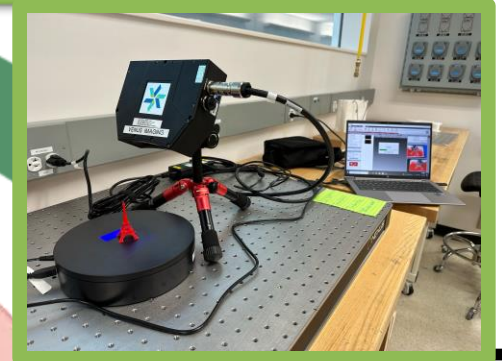


Fig. 16. Variation of the standard deviation of the reconstructed strain as a function of image integration time. Three different sizes of the area used for pixel grouping are used for strain reconstruction, as indicated by the legend (in mm<sup>2</sup>).

# Autonomous Hyperspectral Neutron CT Experiment at ORNL



Light scan and preselection of projection angles

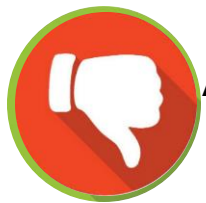


Continue

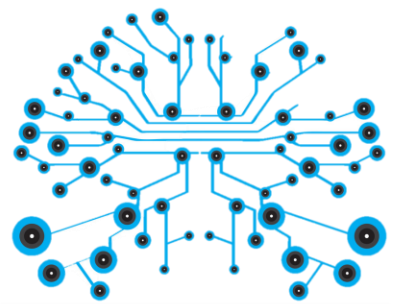
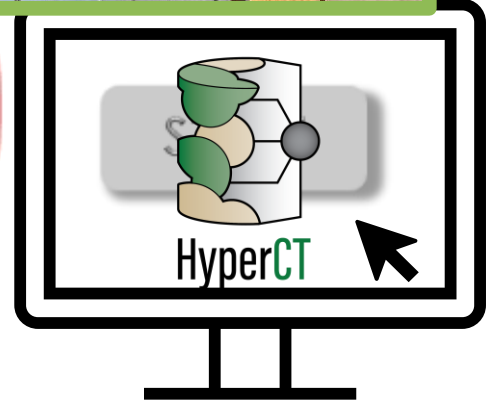
Stop

**Up to factor 5 improvement in time**

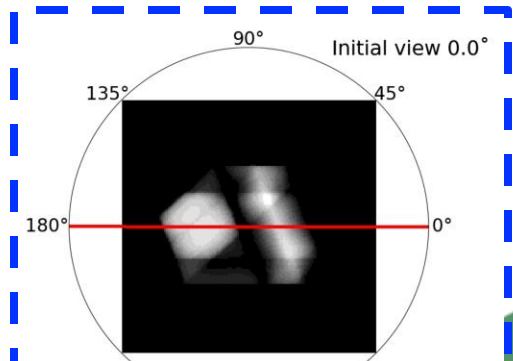
- ▶ Optimization of the scan based on the unique sample geometry
- ▶ Ability to provide real-time reconstructed data using advanced iterative reconstruction methods



Autonomous Decision



AI Quality Evaluation

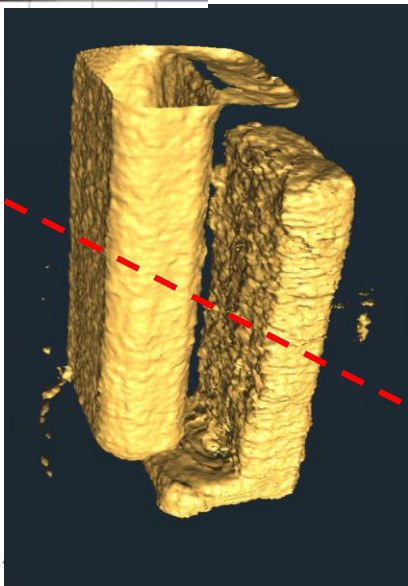
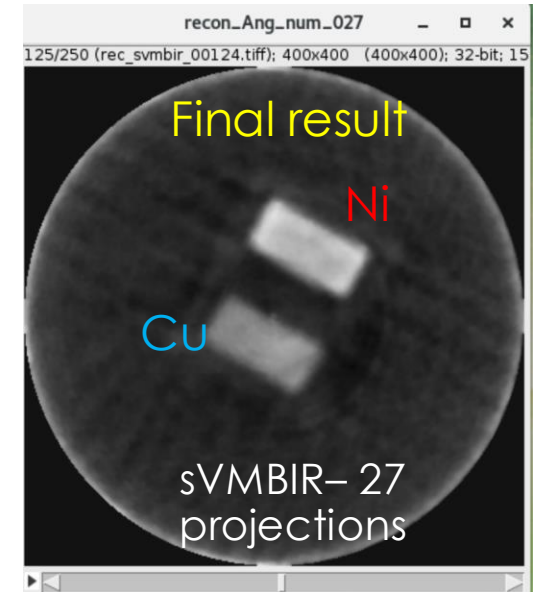
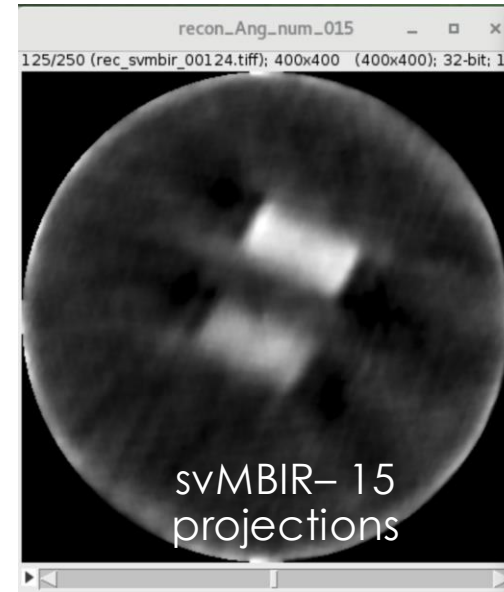
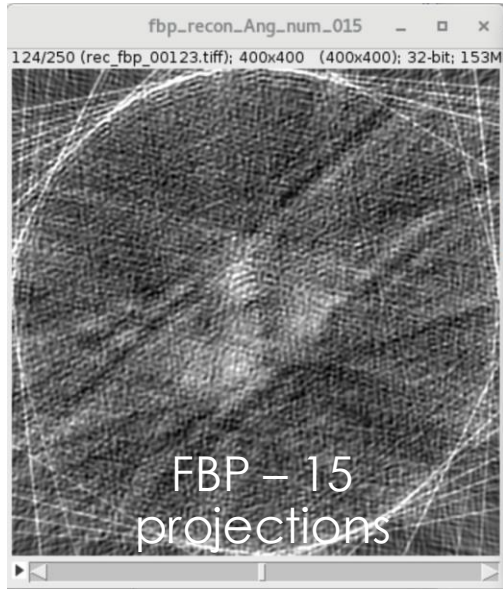


Sample Adaptive Scanning Angles (active learning)

# <311> Bragg edge reconstruction at $\sim 2.17 \text{ \AA} \pm 0.2 \text{ \AA}$

Conventional reconstruction methods

Our advanced algorithms/methods

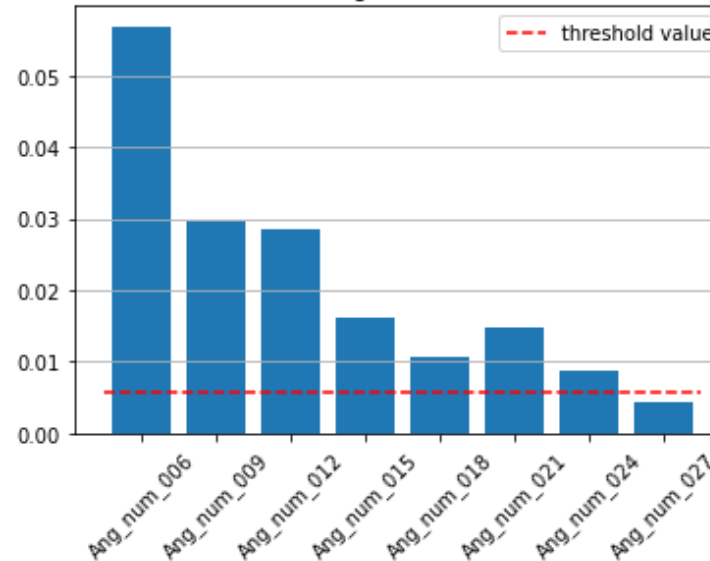


	Thresholds
MSE <sup>1</sup>	$5.689 \times 10^{-3}$
SSIM <sup>2</sup>	0.634

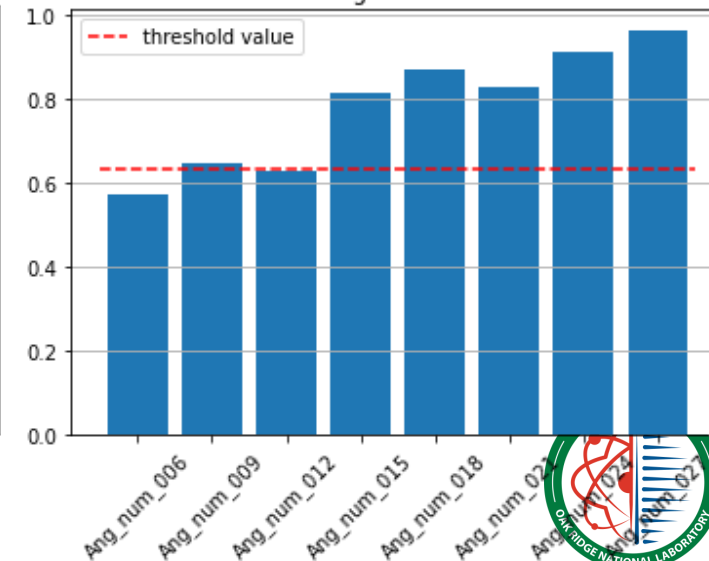
<sup>1</sup>Zhou Wang; Bovik, A.C.; "Mean squared error: Love it or leave it? A new look at Signal Fidelity Measures," Signal Processing Magazine, IEEE, vol. 26, no. 1, pp. 98-117, Jan. 2009.

<sup>2</sup>Z. Wang, A. C. Bovik, H. R. Sheikh and E. P. Simoncelli, "Image quality assessment: From error visibility to structural similarity," IEEE Transactions on Image Processing, vol. 13, no. 4, pp. 600-612, Apr. 2004.

MSE along reconstructions



SSIM along reconstructions



# Neutron Imaging Capabilities at VENUS

- Bragg edge imaging
- Resonance imaging
- Epithermal imaging
- Largest field-of-view thermal/cold imaging
- Neutron grating interferometry (to be implemented)
- Polarized imaging (to be implemented)

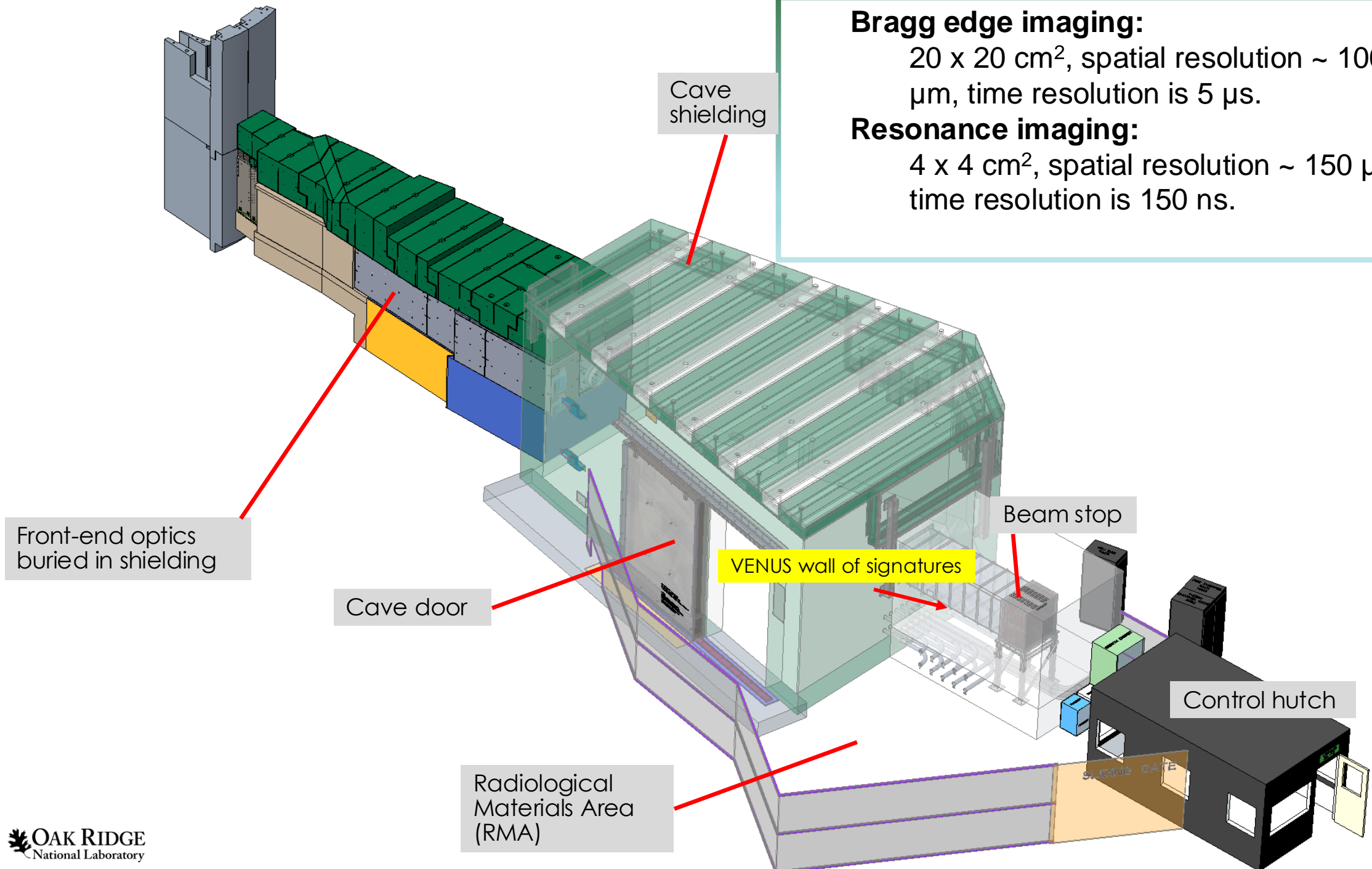


**Bragg edge imaging:**

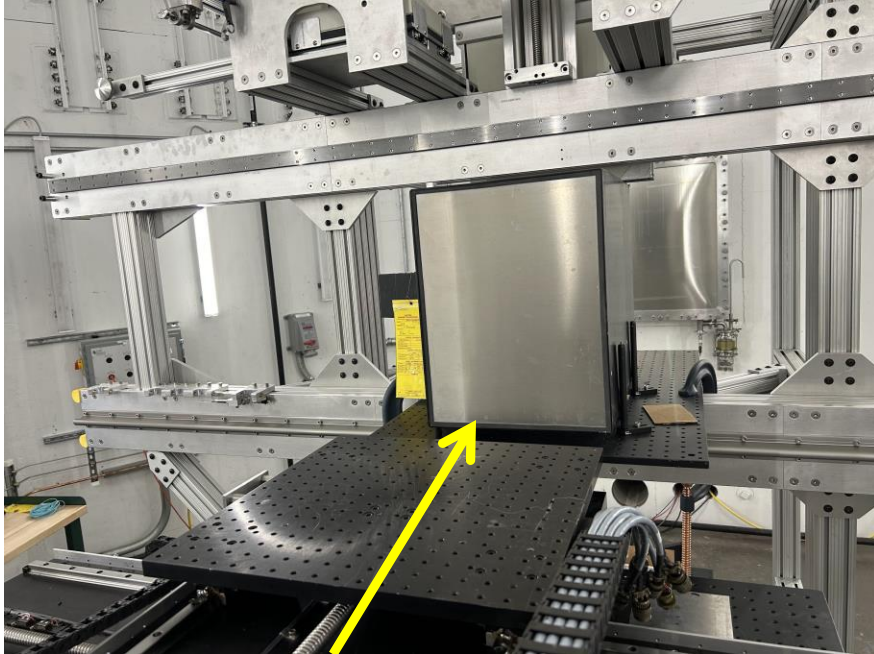
20 x 20 cm<sup>2</sup>, spatial resolution ~ 100 μm, time resolution is 5 μs.

**Resonance imaging:**

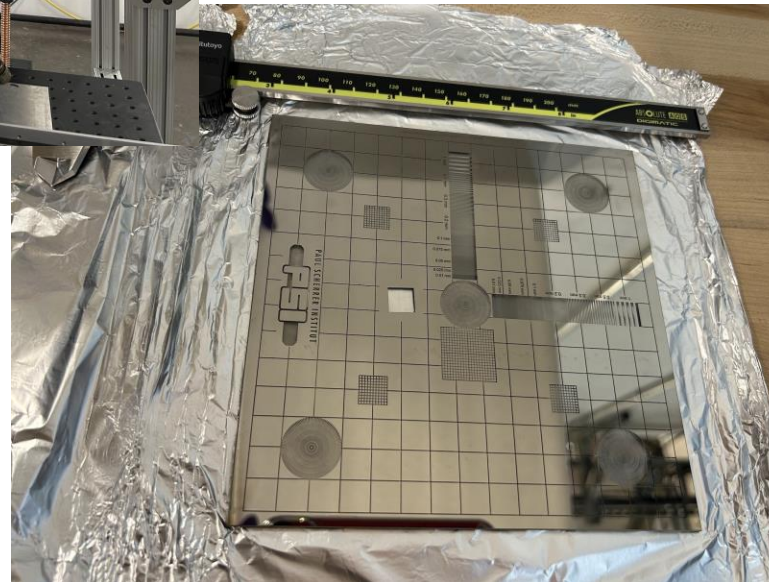
4 x 4 cm<sup>2</sup>, spatial resolution ~ 150 μm, time resolution is 150 ns.



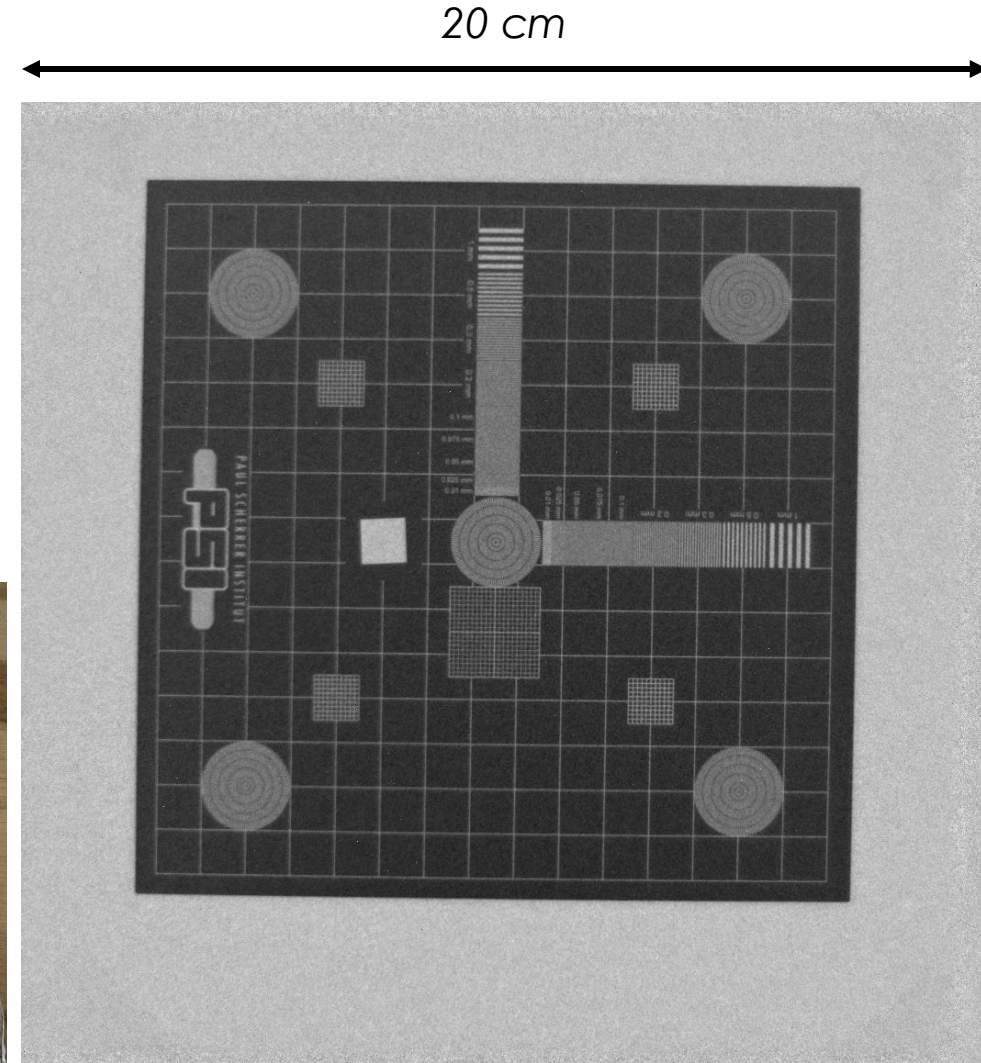
# Largest field of view: 20 x 20 cm<sup>2</sup>



Imaging detector at VENUS



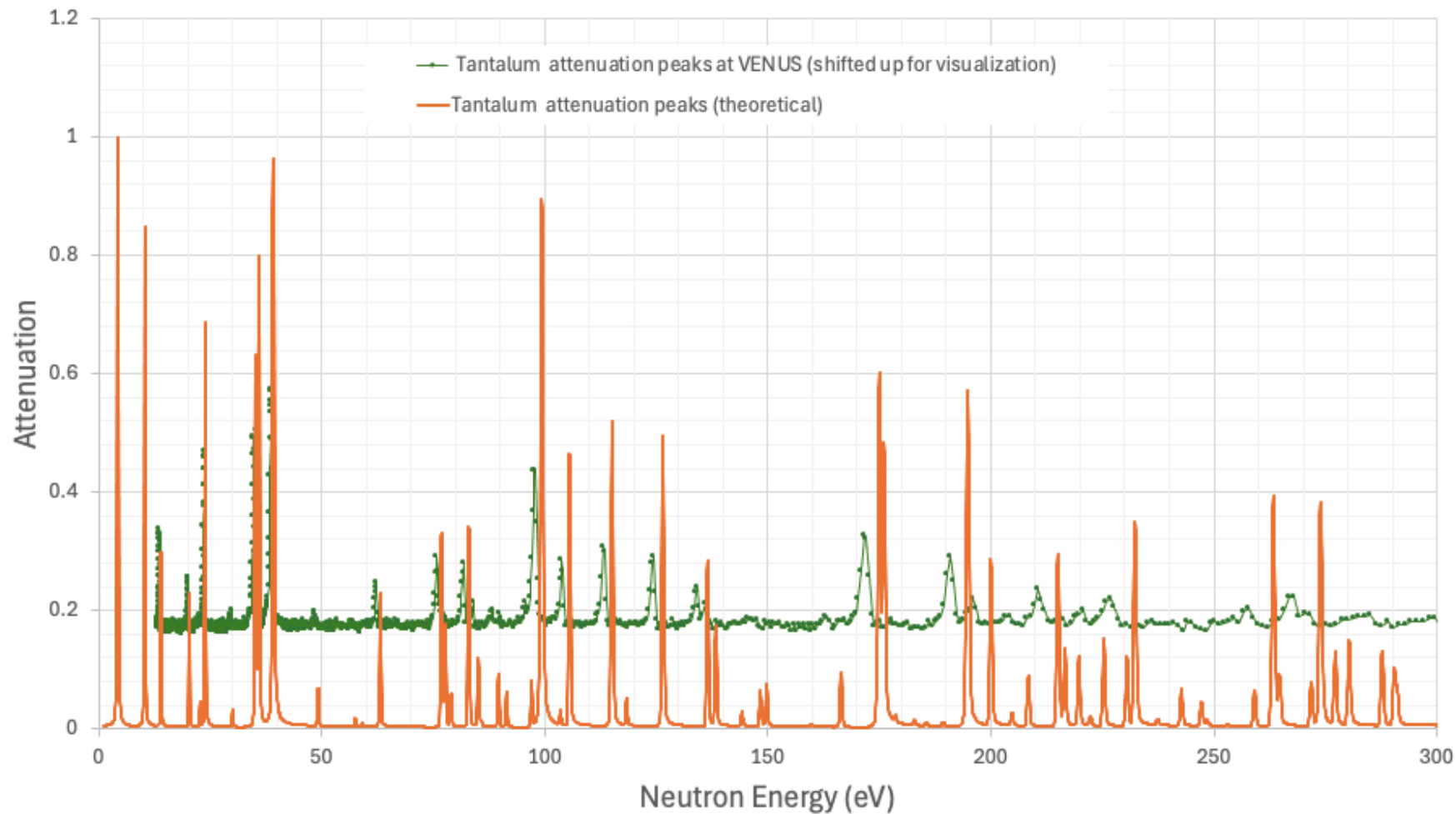
Spatial resolution mask



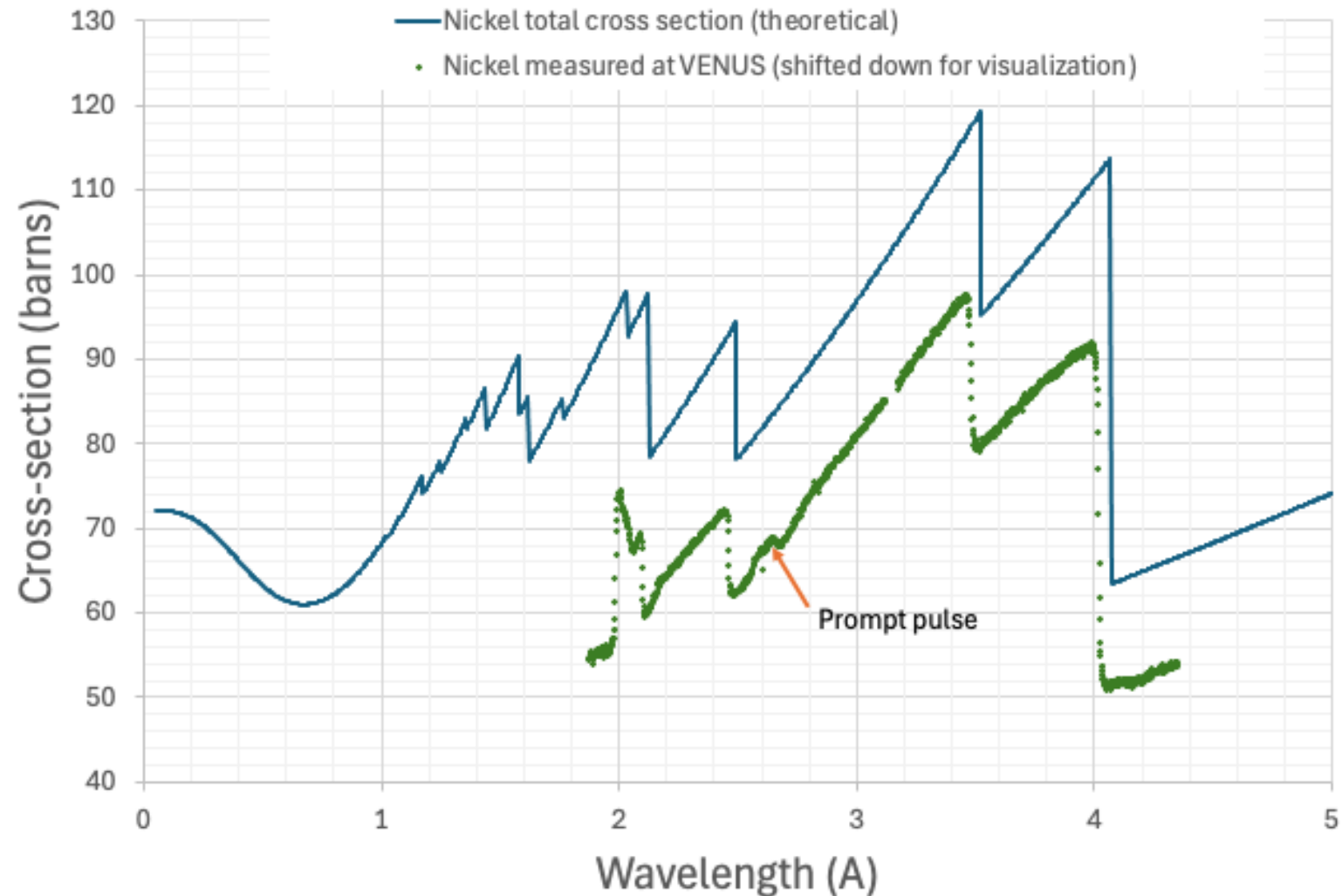
First 20x20 cm<sup>2</sup> large field-of-view radiograph measured at VENUS (July 24, 2024)!!!



# Resonance radiography demonstrated with Tantalum foil and the microchannel plate (MCP) Timepix (TPX) detector



# Bragg edge radiography demonstrated with Nickel powder and the microchannel plate (MCP) Timepix (TPX) detector



# We hope to see you at VENUS!

## The VENUS control hutch



## VENUS



# Outline

- Imaging at the High Flux Isotope Reactor MARS beamline:
  - Principle of neutron radiography and computed tomography at a continuous source
  - The CG-1D imaging beamline
  - Examples
- Imaging at the Spallation Neutron Source:
  - Principle of neutron radiography at a pulsed source
  - Examples
  - ~~The VENUS !!!construction project~~
- **Scientific programming**

Yuxuan

Hassina

Jean



# Scientific programming

## 5 things you must know

Jean Bilheux

Neutron Imaging Computer Instrument Scientist

ORNL is managed by UT-Battelle, LLC for the US Department of Energy



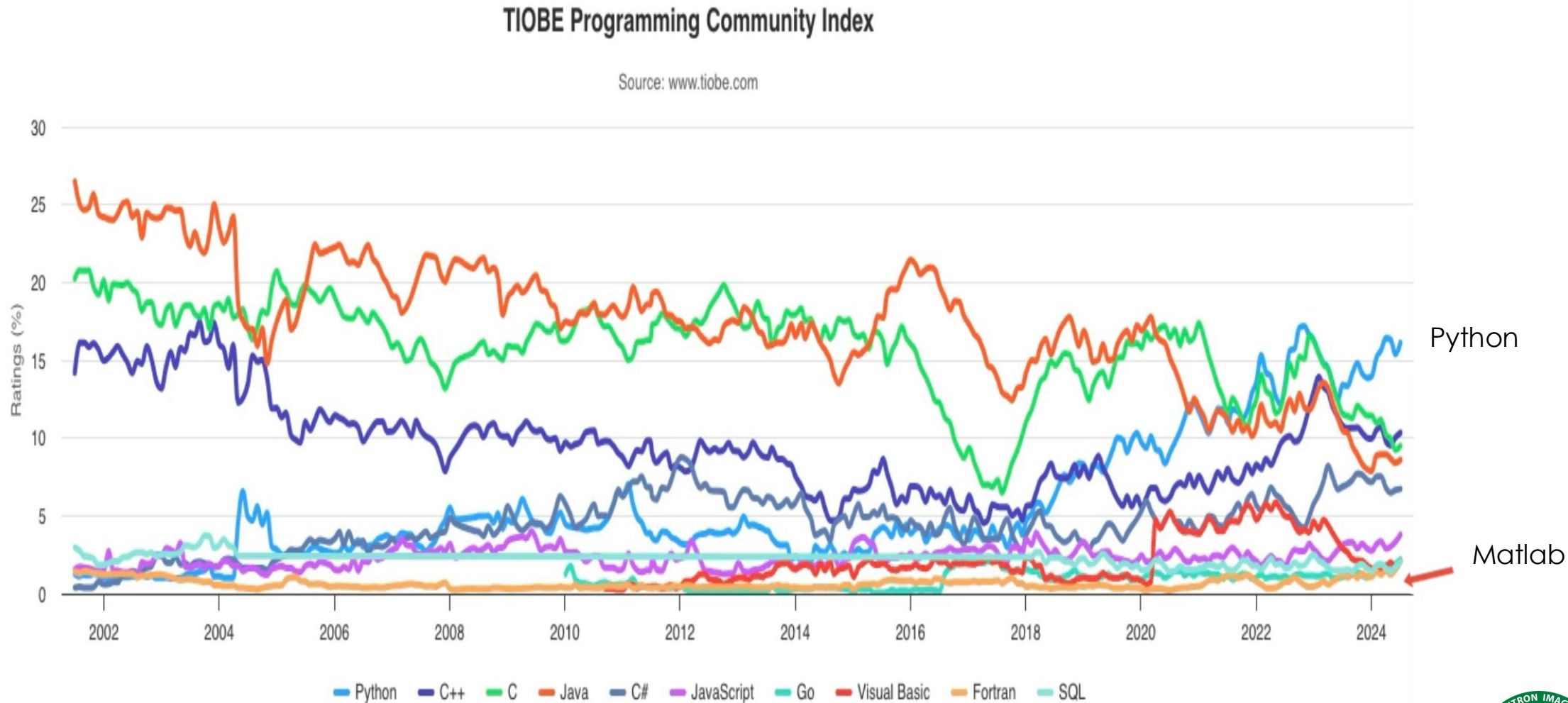
U.S. DEPARTMENT OF  
**ENERGY**

# The 5 things that will save your life

# The 5 things that will save your life








## 1 Pick the right language

# Which language ?





# Which language ?

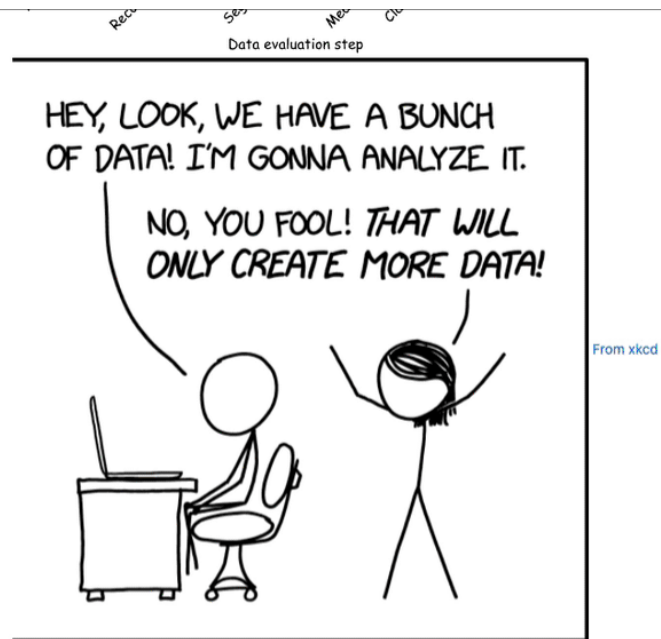
Jul 2024	Jul 2023	Change	Programming Language	Ratings	Change
1	1		 Python	16.12%	+2.70%
2	3	▲	 C++	10.34%	-0.46%
3	2	▼	 C	9.48%	-2.08%
4	4		 Java	8.59%	-1.91%
5	5		 C#	6.72%	-0.15%
6	6		 JavaScript	3.79%	+0.68%
7	13	▲▲	 Go	2.19%	+1.12%
8	7	▼	 Visual Basic	2.08%	-0.82%
9	11	▲	 Fortran	2.05%	+0.80%
10	8	▼	 SQL	2.04%	+0.57%
11	15	▲▲	 Delphi/Object Pascal	1.89%	+0.91%
12	10	▼	 MATLAB	1.34%	+0.08%
13	17	▲▲	 Rust	1.18%	+0.29%
14	16	▲	 Ruby	1.16%	+0.25%
15	12	▼	 Scratch	1.15%	+0.08%
16	9	▼▼	 PHP	1.15%	-0.27%
17	18	▲	 Swift	1.13%	+0.25%

# Python



- Huge community (help, libraries, ...)
- Easy to learn (no compiler needed)
- Easy to build GUI (standalone application, Web interface)
- Run on any platform (    iOS ...)
- Notebooks 

# Notebooks



From xkcd

So... how much is a TB, really?

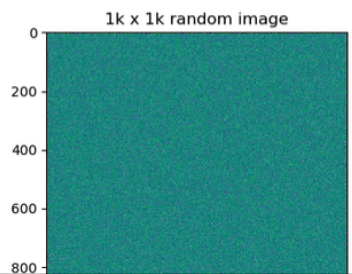
We have been talking about different data amounts of MB, GB, and TB. But, what does that really mean in reality? Let us explore what is a TB.

If you looked at one image with 1024 x 1024 pixels (1 Mpixels)

Here we create one image with 1000x1000 pixels with random values form a uniform distribution [0,1] and show it.

```
In [2]: %matplotlib inline
import matplotlib.pyplot as plt
import numpy as np

plt.figure(figsize=(4,4))
plt.imshow(np.random.uniform(size = (1024, 1024)),
           cmap = 'viridis');
plt.title('1k x 1k random image');
```



# Notebooks


Do not know how to run this notebook? Click ME!

**Notebook Rules**

**Rule 1** Click inside a cell and **SHIFT + ENTER** to execute it.

**Rule 2** Re-executing a cell will reset it (any input will be lost)

**Rule 3** Wait for busy cell signal to go away before executing another cell



**Rule 4** Execute the cells **Top to Bottom**

## 1. Select your IPTS

```
[1]: from __code__ import system
      from __code__.ipywe.myfileselector import FileSelection
      from __code__.profile.profile import ProfileUI

      system.System.select_working_dir(notebook='profile')
      from __code__.__all__ import custom_style
      custom_style.style()

** Using Debugging Model **
Select Instrument
CGID
SNAP
VENUS

IPTS- 

OR

Select Folder
IPTS-19621-compass
IPTS-19921
IPTS-20267
IPTS-20748-Frederik
IPTS-23788
IPTS-24863-test-imars3d-notebook
IPTS-25696-guang
IPTS-26647-grating
IPTS-27158
IPTS-27829
IPTS-27939-cylindrical_correction
IPTS-28170-test_ct_reconstruction
IPTS-29298
IPTS-30610
IPTS-30750
IPTS-31148
IPTS-31601-meqan

HELP
```

[1]:

## 2. Python Import



# The 5 things that will save your life

1 Pick the right language

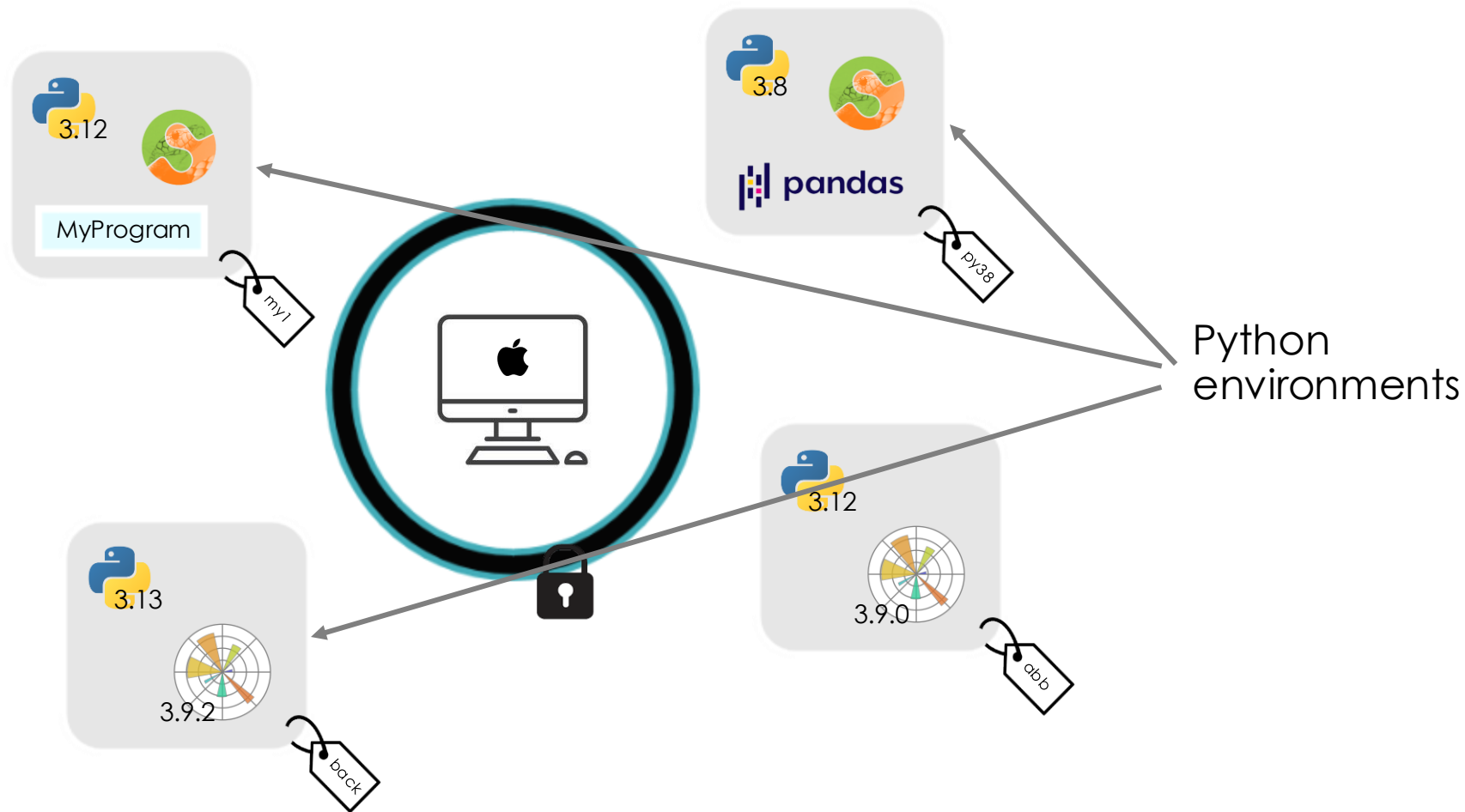
2 **Stay green**

# Stay green

We need to preserve our **environment!**



Anaconda.com

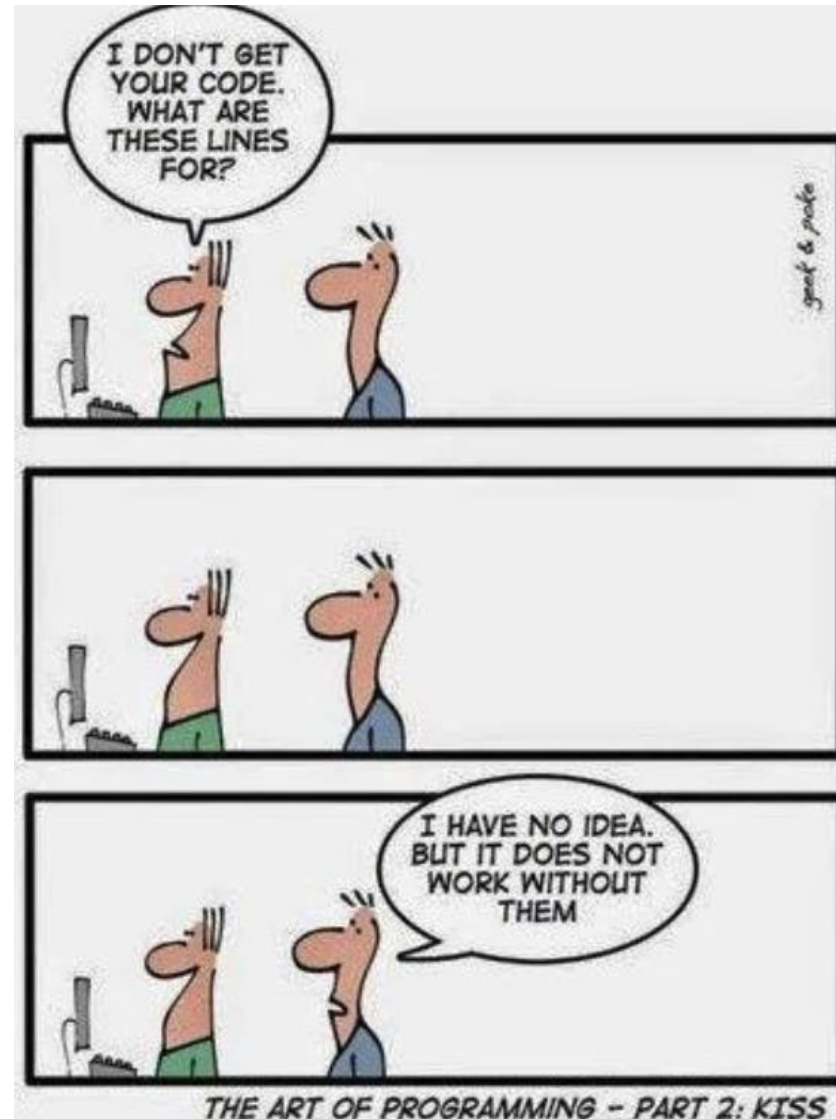


# The 5 things that will save your life

- 1 Pick the right language
- 2 Stay green
- 3 **Write good code**



# Write good code

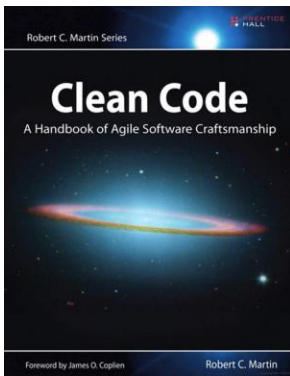


There is a good chance that later, you will be the one trying to understand your own code.

# Write good code

# Naming & Documentation

- Name of variable is what they represent
- Name of method indicates what they do
- Explain strange choices
- Add examples at top of methods/classes



```
1 #!/usr/bin/env python3
2 # -- coding: utf-8 --
3 """Mars3D: gamma filter module."""
4 import logging
5 import param
6 from imars3d_backend.util.functions import clamp_max_workers
7 import numpy as np
8 import tomopy
9
10
11 logger = logging.getLogger(__name__)
12
13
14 class gamma_filter(param.ParameterizedFunction):
15     """Gamma filter.
16
17     Replace near saturated pixels (due to gamma radiation) with median values.
18     The median filtering is carried out by tomopy.remove_outlier.
19     If selective median filtering is enabled (default), only the pixels greater than the specified threshold are replaced.
20
21     Parameters
22     -----
23     arrays: np.ndarray
24         3D array of images, the first dimension is the rotation angle omega
25     threshold: int = -1
26         threshold for saturation, default is -1, which means using the internally defined threshold (see source code)
27     median_kernel: int = 5
28         size of the median filter kernel, default is 5
29     axis: int = 0
30         axis along which to chunk the array for parallel median filtering, default is 0.
31     max_workers: int = 8
32         number of cores to use for parallel median filtering, default is 8, which means using all available cores.
33     selective_median_filter: bool = True
34         whether to use selective median filtering, default is True.
35     diff_tomopy: float = -1
36         threshold passed to tomopy for median filter based outlier detection. Negative values will use the internal default value (see source code).
37
38     Returns
39     -----
40     np.ndarray
41         corrected 3D array of images, the first dimension is the rotation angle omega
42     """
43
44     arrays = param.Array(doc="3D array of images, the first dimension is the rotation angle omega", default=None)
45     threshold = param.Integer(
46         default=-1,
47         doc="threshold for saturation, default is -1, which means using the internally defined threshold (see source code)",
48     )
49     median_kernel = param.Integer(
50         default=5,
51         bounds=(3, None),
52         doc="size of the median filter kernel, default is 5",
53     )
54     axis = param.Integer(
55         default=0,
56         bounds=(0, 2),
57         doc="axis along which to chunk the array for parallel median filtering, default is 0.",
58     )
59     max_workers = param.Integer(
60         default=8,
61         bounds=(1, None),
62         doc="number of cores to use for parallel median filtering, default is 8, which means using all available cores.",
63     )
64     selective_median_filter = param.Boolean(
65         default=True,
66         doc="whether to use selective median filtering, default is True.",
67     )
68     diff_tomopy = param.Float(
69         default=-1,
70         doc="threshold passed to tomopy for median filter based outlier detection. Negative values will use the internal default value (see source code).",
71     )
```

class `imars3d_backend.corrections.gamma_filter.gamma_filter`(`arrays`, `axis`, `diff_tomopy`, `max_workers`, `median_kernel`, `selective_median_filter`, `threshold`, `name`)

Bases: `ParameterizedFunction`

Gamma filter.

Replace near saturated pixels (due to gamma radiation) with median values. The median filtering is carried out by tomopy.remove\_outlier. If selective median filtering is enabled (default), only the pixels greater than the specified threshold are replaced.

Parameters:

- `arrays` (`np.ndarray`) – 3D array of images, the first dimension is the rotation angle omega
- `threshold` (`int` = -1) – threshold for saturation, default is -1, which means using the internally defined threshold (see source code)
- `median_kernel` (`int` = 5) – size of the median filter kernel, default is 5
- `axis` (`int` = 0) – axis along which to chunk the array for parallel median filtering, default is 0.
- `max_workers` (`int` = 8) – number of cores to use for parallel median filtering, default is 8, which means using all available cores.
- `selective_median_filter` (`bool` = True) – whether to use selective median filtering, default is True.
- `diff_tomopy` (`float` = -1) – threshold passed to tomopy for median filter based outlier detection. Negative values will use the internal default value (see source code).

Returns: corrected 3D array of images, the first dimension is the rotation angle omega

Return type: `np.ndarray`

`imars3d_backend.corrections.intensity_fluctuation_correction.module`

`imars3d`'s intensity fluctuation correction module.

class `imars3d_backend.corrections.intensity_fluctuation_correction.intensity_fluctuation_correction`(`air_pixels`, `ct`, `max_workers`, `sigma`, `tdqm`, `class_name`)

Bases: `ParameterizedFunction`

Correct for intensity fluctuation in the radiograph.

Parameters:

- `ct` (`np.ndarray`) – The image/radiograph stack to correct for beam intensity fluctuation.
- `air_pixels` (`int` = 5) – Number of pixels at each boundary to calculate the scaling factor. When a negative number is given, the auto air region detection will be used instead of tomopy.
- `sigma` (`int` = 3) – The standard deviation of the Gaussian filter, only valid when using the auto air region detection via canny edge detection from skimage.
- `max_workers` (`int` = 8) – The number of cores to use for parallel processing, default is 8, which means using all available cores.
- `tdqm`, `class` (`panel.widgets.Tdqm`) – Class to be used for rendering tqdm progress.

Return type: The corrected image/radiograph stack.

`imars3d_backend.corrections.intensity_fluctuation_correction.intensity_fluctuation_correction.skimage_image`(`ndarray`, `sigma`: `int` = 3) → `ndarray`

IFC via skimage.

Correct for intensity fluctuation in the radiograph using skimage to auto detect the air region (adapted from `imars3d.v1.filter.IFC`).

Parameters:

- `image` (`np.ndarray`) – The image/radiograph (2D) to correct for beam intensity fluctuation.
- `sigma` (`int`) – The standard deviation of the Gaussian filter for the canny edge detection.

Return type: The corrected image/radiograph (2D).

Notes

This method here is assuming the beam is decaying uniformly over time whereas the tomopy version is assuming different region decays slightly different, hence the linear interpolation between left and right air pixels. In most cases, a uniform decay is a good approximation as neutron beam tends to be very stable.

class `imars3d_backend.corrections.intensity_fluctuation_correction.normalize_raw`(`ct`, `max_workers`, `roi`, `name`)

Bases: `ParameterizedFunction`

Normalize raw projection data to give an average of a selected window on projection images.



# Write good code

## Workflow

- decide the code to write
- Write the test
- It should fail
- Write the code to pass the test
- It should pass
- Move on to the next one



## Advantages

- The unit tests are often used as documentation to learn how the software works
- You write better code (simpler)
- People will trust your code
- You can check the unit test coverage
- Later on, when you make changes, you will quickly find out if the software still works
- If someone report a bug, first write a unit test to reproduce the bug, then fix it!

## Disadvantages

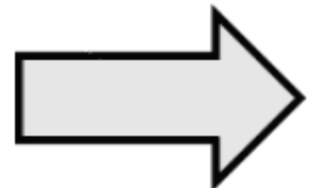
- It seems slower to code (but overall, it's not)



# Write good code



- Code
- Unit tests
- Documentation
- License file
- Future work file
- ...



JOSS

Software X

F1000Research

DOI

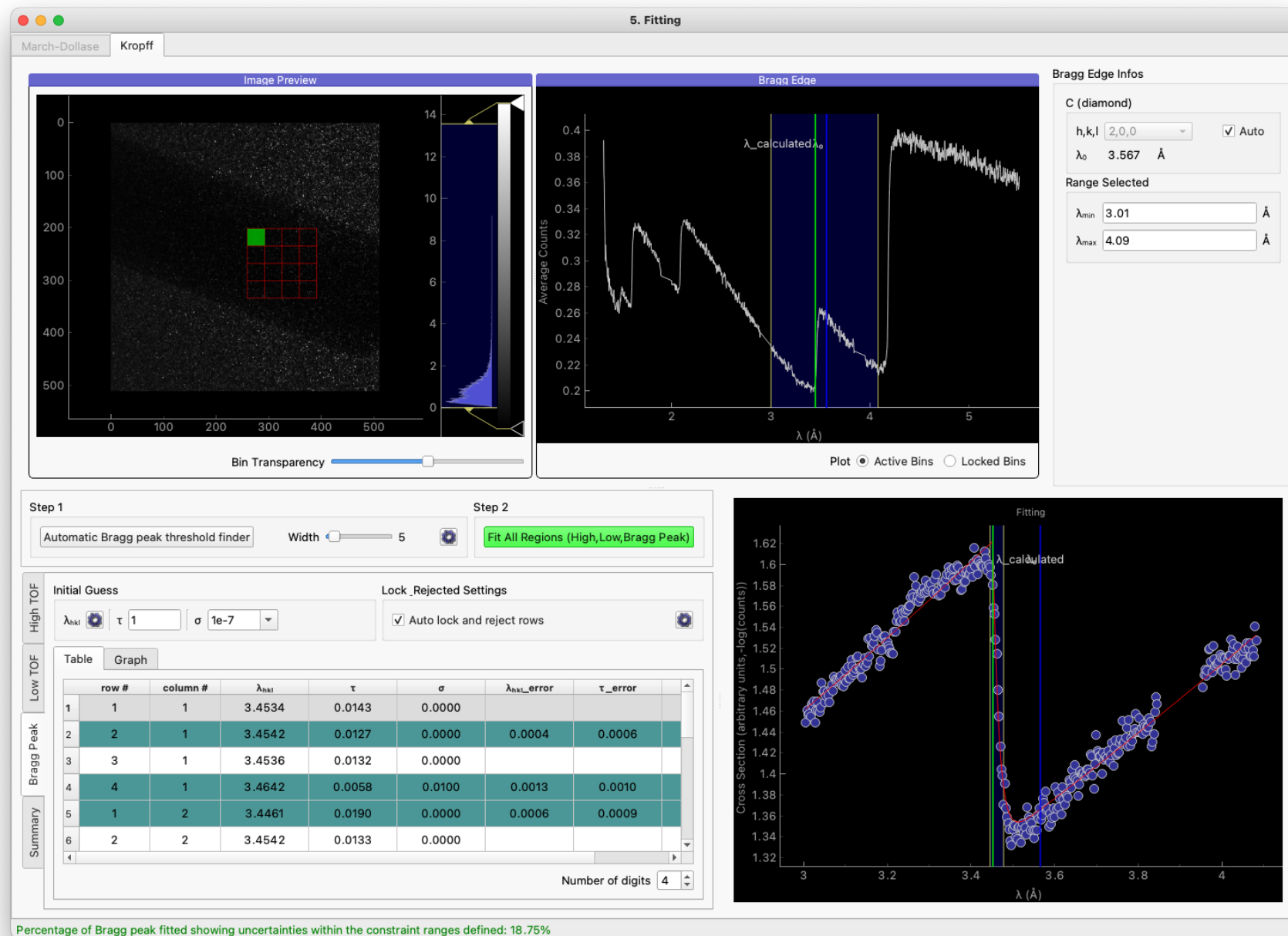
**Getting a publication out of your software !**

# The 5 things that will save your life

- 1 Pick the right language
- 2 Stay green
- 3 Write good code
- 4 **How to keep your job!**

# iBeatles

- Program that perform automatic **strain mapping calculation**
- 1 million lines of code
- 5 years development
- Kept top secret until today (**only copy** is on this machine!)



# iBeatles

Demo time !

# iBeatles

Demo time !



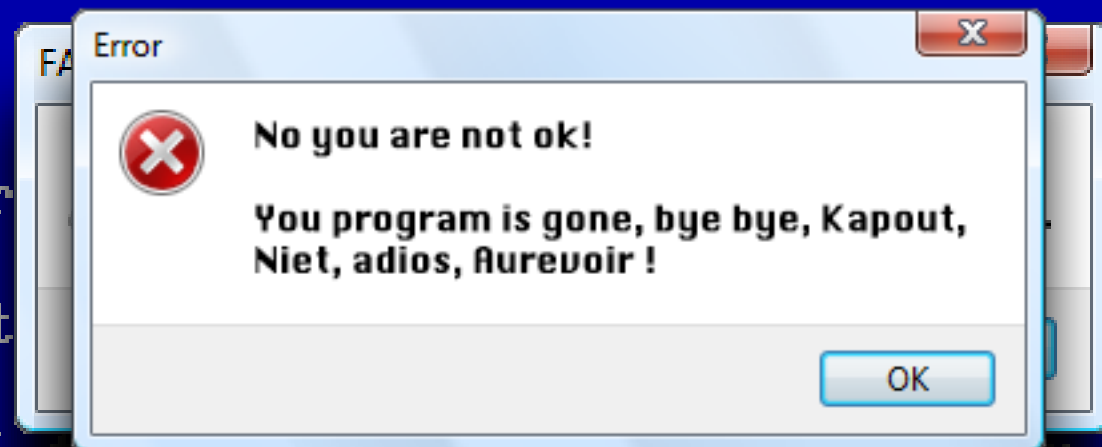
An error has occurred

Press Enter to return

Press CTRL+ALT+DEL

you will lose any unsaved information in all open applications.

Error: 0E : 016F : BFF9B3D4



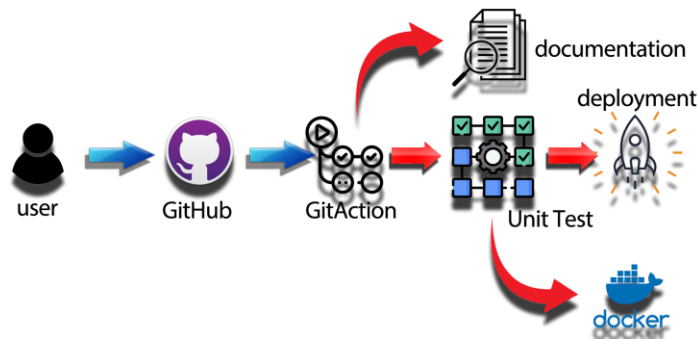
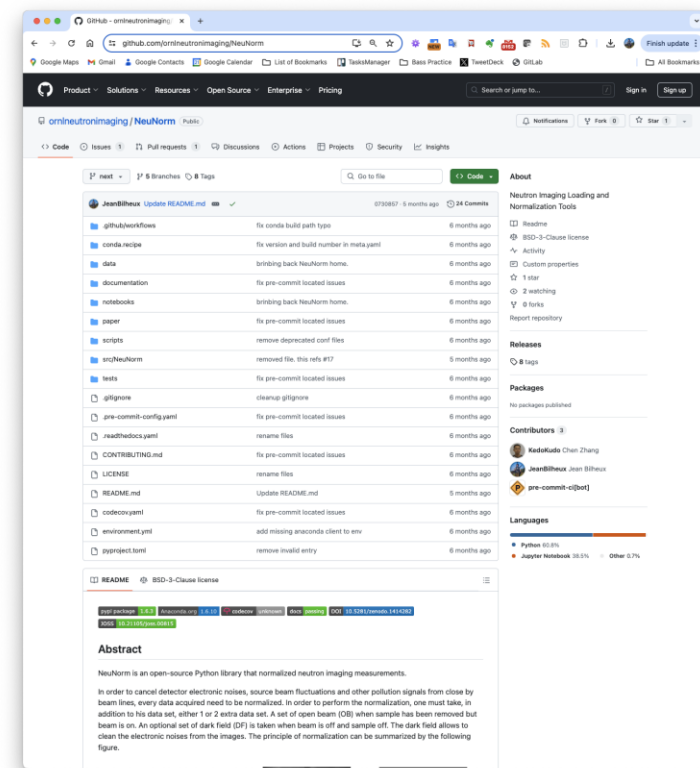
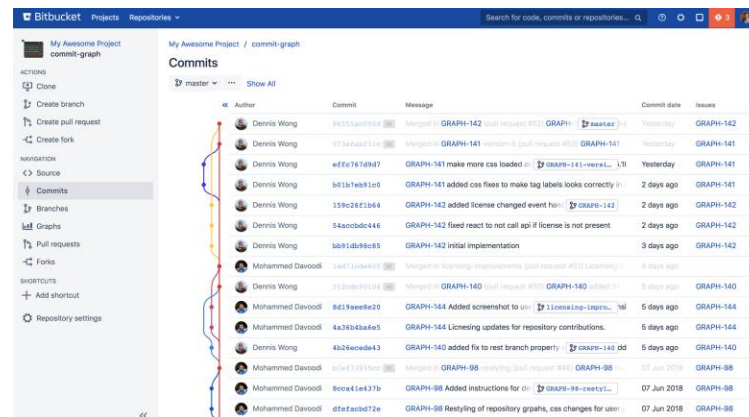
Press any key to continue \_



# Repositories



- Backup of your project
- Provide a full history (easy to reverse changes, ...)
- Ideal for collaboration (parallel work, ...)
- Documentation
- Necessary tool for publication of the code
- Easy to share code (web interface, ...)
- GitAction (automatic test, deployment, build documentation ....)







# The 5 things that will save your life

- 1 Pick the right language
- 2 Stay green
- 3 Write good code
- 4 How to keep your job!
- 5 **Use the best debugging tool**

# Best debugging tool



- Any OS    
- Any computing language
- It takes no time to learn how to use it
- It never needs any software update
- It has a very small carbon footprint

Each of you will  
leave today with  
that tool!

**YOU'LL THANK ME LATER**



# Best debugging tool



- Tell your new friend what your program does, and you will find what is wrong with it !



## The Yellow Duck

# The 5 things that will save your life

- 1 Python
- 2 use environments
- 3 Good naming & unit tests
- 4 Repository
- 5 Talk to your yellow duck

# Acknowledgements



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<https://forms.office.com/g/gtdnJGM87r>

Thank you

Questions

NXS Lecture - Yuxuan Zhang,  
Hassina Bilheux & Jean Bilheux:  
"Neutron Imaging"



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